

# Multilevel Thresholding using PSO Clustering

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## ABSTRACT

Thresholding algorithms are quite easy and effective for bi-level thresholding but in case of multilevel thresholding, the performance becomes unreliable due to complexity in computation because the complexity will exponentially increase. In this approach, multilevel thresholding is done for comparison by taking help of Otsu's clustering method and PSO clustering method. A dendrogram of gray levels is created based on histogram of an image. The bottom-up generation of clusters employing a dendrogram by the proposed method yields good separation of the clusters and obtains a robust estimate of the threshold. Such cluster organization will yield a clear separation between object and background even for the case of nearly unimodal or multimodal histogram. Since the hierarchical clustering method performs an iterative merging operation, it is extended to multi-level thresholding problem by eliminating grouping of clusters when the pixel values are obtained from the expected number of clusters.

**Keywords** – segmentation, thresholding, pso-clustering, histogram, Otsu's clustering, dendrogram

## 1. INTRODUCTION

The objective of segmented image [2] is to extract the required objects from an input image. Image segmentation is one of the most difficult partition task. The more efficient solution depends on the output of segmentation process. In addition the task of computer vision, including feature extraction, model matching and object recognition, heavily depends on the quality of the image segmentation process. Image based thresholding is a simple but effective tool for image segmentation.

Due to its simplicity thresholding[3] is more practical for real-time implementation. The purpose of bilevel thresholding or multilevel thresholding operation is that objects and background are separated into non-overlapping sets. The output of the thresholding operation is a binary image and in many image processing applications, the use of binary images can decrease the computational cost of the compared to gray-level images.

Although the thresholding[3] appears simple, it is very important and fundamental with the wide applicability, as it is relevant not only for segmenting the original image data but also for segmenting its linear and non-linear image to image transforms.

Clustering is considered as a task to organize a data set into a number of groups such that patterns within a cluster are more similar to each other than the patterns or features belonging to different clusters. In other words, clustering is an important technique as clustering-based methods[4] where the gray level samples are clustered in two parts as background (object) and

foreground (object). In partitioning based clustering, the algorithm arranges all the objects into various partitions, where total number of partitions is less than the total number of objects. For a database of "n" objects can be arranged into "k" partitions, where  $k < n$ . Here each partition represents a cluster. The partition depends upon a function, called as similarity function and this similarity function is the criteria based on which clusters are formed.

## 1.1 CLUSTERING THRESHOLDING OF OTSU

Otsu[11]'s method implements by minimizing the weighted sum of within-class variances of the foreground and background pixels to establish an optimum threshold. Since minimization of within-class variances is tantamount to the maximization of between-class scatter, the choice of the optimum threshold can be formulated as :

$$T_{opt} = \arg \max [P(T).(1 - P(T)).(m_f(T) - m_b(T))^2] \quad (1)$$

The Otsu method gives satisfactory results when the numbers of pixels in each class are close to each other. The Otsu will remain one of the most referenced thresholding methods.

## 1.2 PARTICLE SWARM OPTIMIZATION (PSO)

Particle Swarm Optimization (PSO) is a population-based stochastic search process, modeled after the social behavior of a bird flock. The algorithm maintains a population of particles, where each particle represents a potential solution to an optimization problem. In the context of PSO[5], a swarm refers to a number of potential solutions to the optimization problem, where each potential solution is referred to as a particle. The aim of the PSO[5] is to find the particle position that results in the best evaluation of a given fitness (objective) function. Each particle represents a position in  $N_d$  dimensional space and is "flown" through this multidimensional search space, adjusting its position towards both.

- the particle's best position found so far
- the best position in the neighborhood of that particle

Each particle  $i$  maintains the following information:

- $x_i$ : the current position of the particle
- $v_i$ : the current velocity of the particle
- $y_i$ : the personal best position of the particle

The local best position of the  $i_{th}$  particle is obtained as :

$$pbest_i(t+1) = \begin{cases} pbest_i(t), & \text{if } F(x_i(t+1)) > F(pbest_i(t)) \\ x_i(t+1), & \text{if } F(x_i(t+1)) < F(pbest_i(t)) \end{cases} \quad (2)$$

and the global best position is obtained as

$$\hat{g}best(t) = \min \left\{ F(pbest_0(t)), F(pbest_1(t)), \dots, F(pbest_s(t)) \right\} \quad (3)$$

where  $F$  denotes the fitness factor of the particles and is obtained from Euclidian distance.

The modified velocity and position of each particle at the time  $(t+1)$  can be calculated as

$$v_i(t+1) = K \cdot \left[ w(t) \cdot v_i(t) + c_1 \cdot rand_1 \cdot (pbest_i - x_i(t)) + c_2 \cdot rand_2 \cdot (pbest_g - x_i(t)) \right] \quad (4)$$

Two basic approaches to PSO exist based on the interpretation of the neighborhood of particles. Equation (3) reflects the gbest version of PSO[5] where, for each particle, the neighborhood is simply the entire swarm. The social component then causes particles to be drawn toward the best particle in the swarm. In the lbest PSO model, the swarm is divided into overlapping neighborhoods, and the best particle of each neighborhood is determined. For the lbest PSO model, the social component of equation (5) changes to

$$c_2 \cdot rand_{2,k}(t) (y_{j,k}(t) - x_{i,k}(t)) \quad (5)$$

where  $y_j$  is the best particle in the neighborhood of the  $i$ -th particle.

The PSO is usually executed with repeated applications (2) to (5) until a specified number of iterations have been exceeded.

### 1.3 PROPOSED CLUSTERING BASED MULTICLASS THRESHOLDING

In the approach, all dendograms have been developed from the gray level histograms. The bottom-up generation of clusters employing the dendograms by the proposed method i.e. Otsu's method[6][7] yields a good separation of the clusters and obtains a robust estimate of the threshold. Such a type of clustering approach will yield a threshold to clearly separate the multi-modal objects (as below figures) and the background of the same. Since, this approach initially treats each non empty gray level in the histogram as a single cluster and then successively merges clusters until all points have been merged therefore, this approach is suitable for multi level thresholding problem. The images are scanned as colored images. Then Otsu's method is applied to the scanned the multimodal colored images for Otsu's threshold measurement. After that the output images are converted to

black and white (BW) images[8] of the source colored multimodal images of class logical. It converts the source color images in the below pictures to the respective binary image. The output images i.e. Black and White(BW) replaces all pixels in the input images with the luminance greater than level with the value 1 (white) and replaces all other pixels with the value 0(black).



Figure 1.Source First Set of Color Images (GIF, JPEG) and Converted Black and White Image

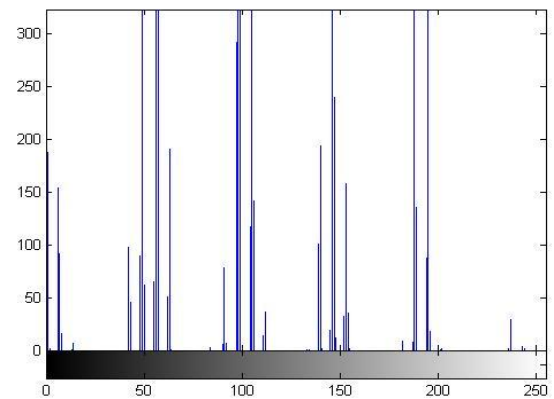


Figure2. Histogram of GIF in figure1

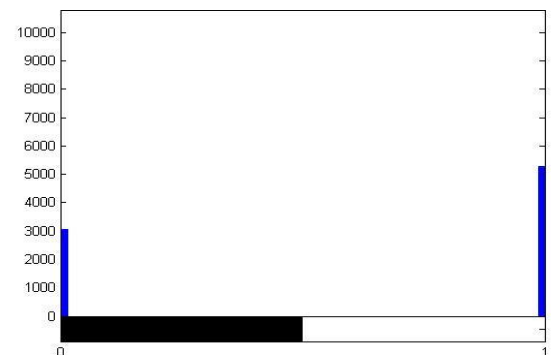


Figure3.Histogram of BW in figure 1

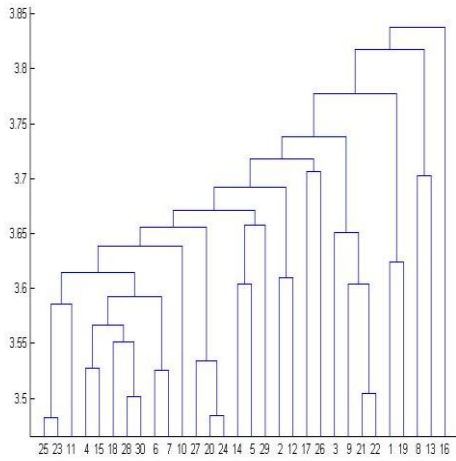


Figure 4. Dendrogram of images in figure 1

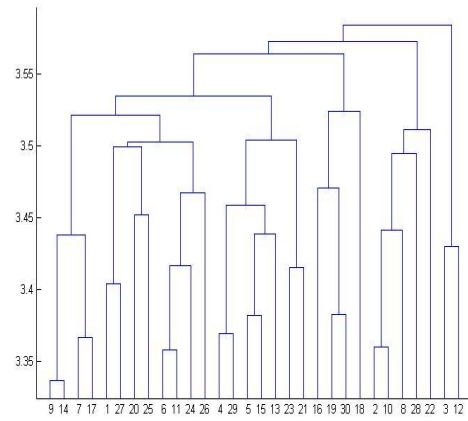


Figure 8 Dendrogram of images in figure 5



Figure 5. Source Second Set of Color Images (GIF, JPEG) and Converted Black and White Image



Figure 9 Source Third Set of Color Images (GIF, JPEG) and Converted Black and White Image

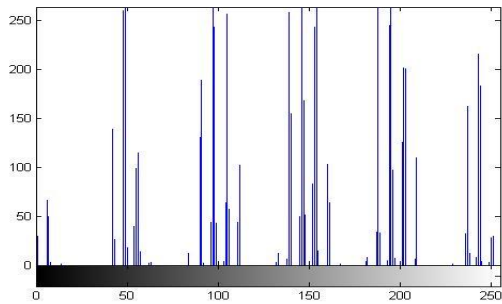


Figure 6. Histogram of GIF in figure 5

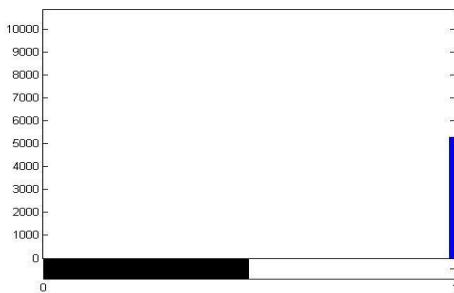


Figure 7. Histogram of BW in figure 5

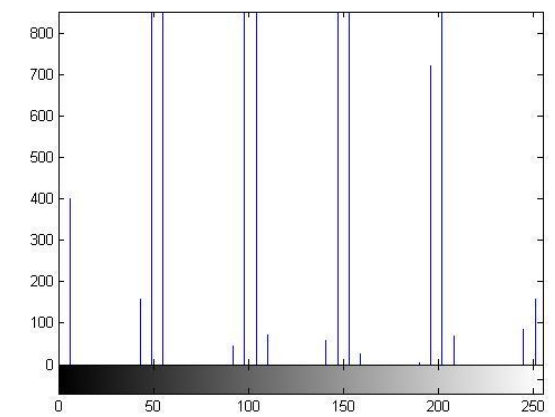


Figure 10 Histogram of GIF image of figure 9

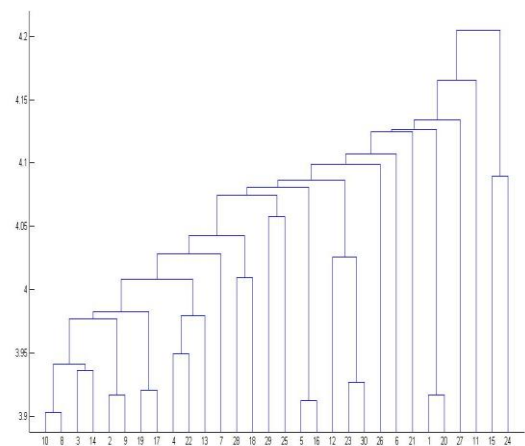


Figure11 Dendrogram of images in figure 9



Figure12 Histogram of BW images in figure 9

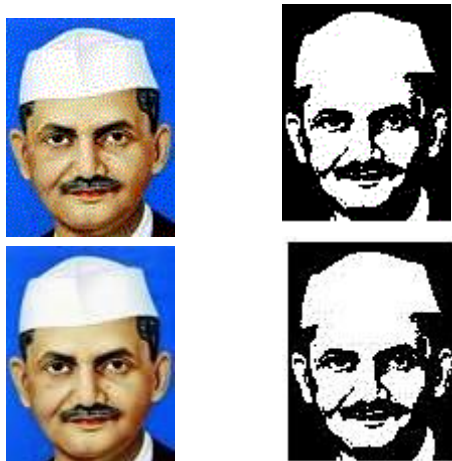


Figure13 Source Fourth Set of Color Images (GIF, JPEG) and Converted Black and White Image

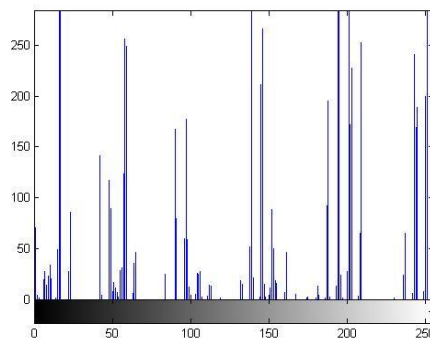


Figure 14 Histogram of GIF image in figure 13

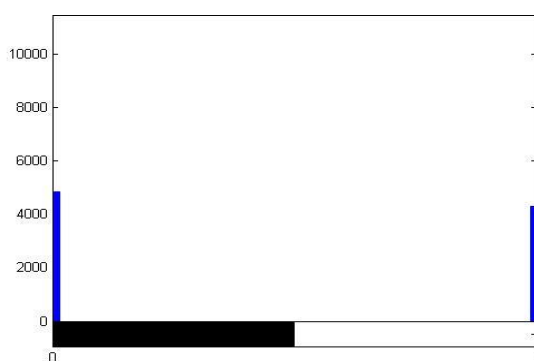


Figure15 Histogram of BW images in figure 13

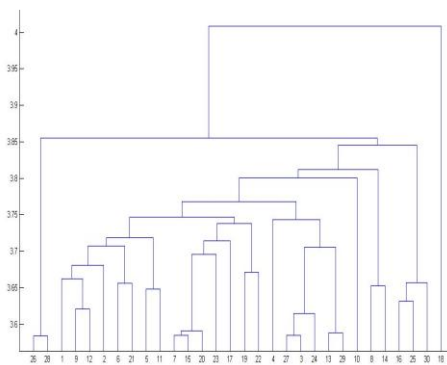


Figure16 Dendrogram of images in figure 13



Figure 17 Source Fifth Set of Color Images (GIF, JPEG) and Converted Black and White Image

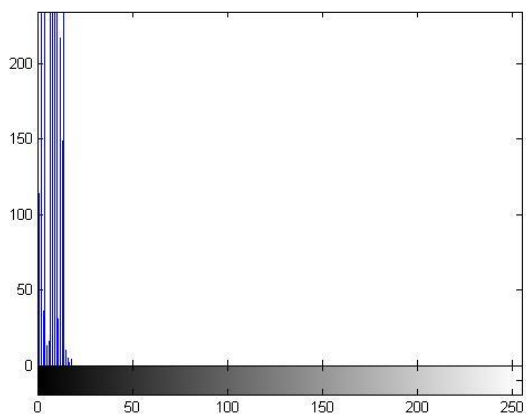


Figure 18 Histogram of GIF image in figure 17

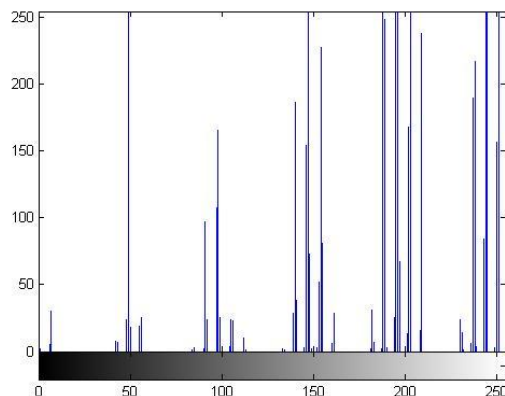


Figure 22 Histogram of GIF image in figure 21

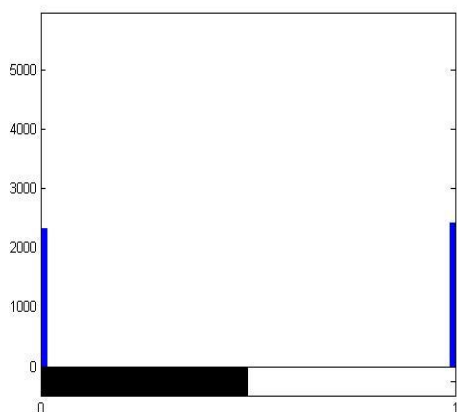


Figure19 Histogram of BW image in figure 17



Figure 23 Histogram of BW image in figure 21

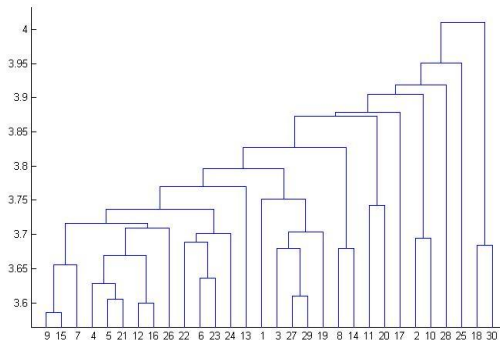


Figure 20 Dendrogram of images in figure 17

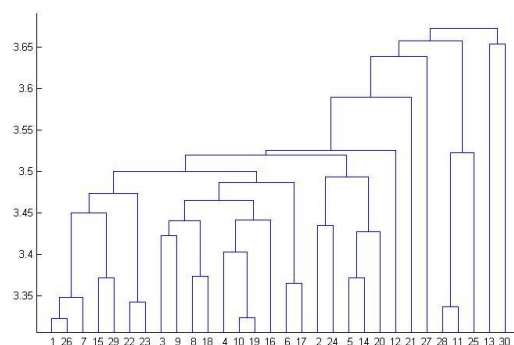


Figure 24 Dendrogram of image in figure 21



Figure 21 Source Sixth Set of Color Images (GIF, JPEG) and Converted Black and White Image

## 7. CONCLUSION

Otsu's method for image segmentation is very time-consuming because of the inefficient formulation of the between-class variance. A faster version of Otsu's[9][10][11] method is implemented for improving the efficiency of computation for the optimal thresholds. A criterion for maximizing a modified between-class variance that is equivalent to the criterion of maximizing the usual between-class variance is proposed for image segmentation[12][13][14]. Next, in accordance with the new criterion, a recursive algorithm is designed to efficiently find the optimal threshold.

The analysis of the new criterion clearly shows that it takes less computation to compute both the cumulative probability i.e. zeroth order moment and the mean of a class.

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