Using Fuzzy Center Mean (in general any) Clustering Methods to Construct Fuzzy Classifier Tuned to do Classification

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ABSTRACT

This about paper presents using FuzzyCentreMean[1][4][5][7][8] (in general any clustering method) to construct fuzzy classifier tuned to do classification. Clustering methods, in general try to form clusters of data in such a way that a huge chunk of data is reduced to its representative elements(sets). The different clustering methods are like different points of view of the same data[1][4][5][7][8]. For Fuzzy classifier decision making/logic is imparted by 'Rules of inferences' framed by expert human pertaining to data considered. This paper provides a way to construct the rules of inference without the need of humanly intervention but by interpreting data centers of the clusters[1][3][6][11] .The above case is mainly important in almost lossless data compression, in reconstruction of an entire image/video from the damaged copy and in areas of classification of data points into appropriate classes(similar to classes designed by humans manually after interpreting the data). The case study here, is on fisher Iris data set[9].

General Terms

Fuzzy classifier algorithms, Data classification, Data compression, Data reconstruction, Data cluster.

Keywords

fuzzy, fuzzy clasifier,cluster,rules of inference, data point, data center,membership,mamdani type, fuzzy center mean, Fuzzy classifier algorithms

1. INTRODUCTION

The driving philosophy of bringing out relationship between clustering techniques and design of fuzzy classifier, rather "Rules of inference" in specific is just in support for the way "Great Neural Network" (Humans) work.

People learn things by "Association" (Associative learning); and, so they learn classifying similar with dissimilar.[2]

Also, one important point to be noted is that when same information is given to many individuals each individual may develop different interpretation and hence different viewpoint.[2] The different clustering methods are like different points of view for the same data[1][2][4][5]. So, choice of clustering methods to meet particular design ends of controller also matters greatly. And, writing about "Association", there is a classic theorem called "Sampling theorem" which says that exact reconstruction of continuous signal from discrete signal points sampled in time is possible .But for this to happen the instants of sampling should be right(as defined by the conditions of the above said theorem)[5]. According, to my interpretation, these sampled time instants can be considered as "Associating-links" between data points such that we are able to construct(learn) the entire function(of continuous kind).So, if data compression is considered equivalent to sampling and (exact) data reconstruction is considered equivalent to interpolation. Then knowledge about distribution of data point around each data center(found from clustering methods) or I can call it noise around data centers. These data centers are like "associative-links" similar to sampling time instants, which might help in associating each data center and by "fuzzying" around them we might reconstruct entire data without any loss.(i.e., equivalent to interpolation or finding values in between sampled signals). I have devised my own two algorithms-one on formulating "rules" based on (primitive/in general, may use advanced) statistical properties of data (like mean, cluster center, relative distance). And the second algorithm focuses on forming what I call "group(class)-feature matrix" based on the results of clustering methods which is made use in devising "Rules of inferences" for Fuzzy controllers/classifiers(most critical/difficult part in design of this controllers). An algorithmic approach is followed to tackle this task of tuning of fuzzy controller/classifier, also in situations where I found scope for generalizing, I took the liberty to do so. And in other situations I would choose to limit my interpretation rather study to "fisheriris" data set[4].

2. Fuzzy Classifier

This classifier has its foundations in fuzzy logic and mamdani fuzzy logic controller.[1][3][11]

2.1 Fuzzy Logic and Mamdani fuzzy logic controller

Fuzzy logic is a form of multivalued-logic, the truth values in this case ranges between 0-1 rather than conventional 1(true) or 0(false) and hence reasoning is more approximate and not exact[1][3][11]. Mamdani fuzzy logic controller is a logic controller implemented on fuzzy logic concepts. The main focus of this controller are the "Rules of inferences" which deals with making decision on a data sample based on expert human knowledge in the particular field under consideration[1][3][11]. These rules are the most difficult aspect of the design and construction of such controllers/classifiers. This paper attempts to make human interpretation on data and the knowledge based on their experience unnecessary but instead the below algorithms forms these rules based on the data's statistical properties and hence derives the interpretations/rules on them without the need of human expert knowledge/experience.(well,there is great amount good literatures on fuzzy sets and logic. This work's referencesSo,here I would cut the chase and come directly to the algorithms on constructing fuzzy classifier.)

3. Begin:

1)Arrange data set in a matrix of this form as shown below-

A=

No.	Feature1	Feature n	Output1	Output k
(Datapoint)1				

Dimensions of this matrix=(no. Of datapoints * (no. Of features +no. Of outputs));

If outputs are absent then -

A=

No.	Feature1	Feature 2	Feature 3	Feature n
(Datapoint)1				

Dimensions of this matrix=(no. Of datapoints * no. Of features);

2)Every classification problem specifies no. And type of groups present.

Form a matrix such that each row of which should stand/labelled for group/class and each column should stand/labelled as features involved.

Each cell of the matrix should contain a (statistical) quantity which represent each group's each feature's value.

In this case,for initialising this matrix(G) ,I took for each cell "mean" for group say (indexed) "i" and across datavalues for a feature say, "j".So, this matrix contains mean values derived from training set.

G=

Group/class no.	Feature1	Feature j	Feature n
G1			
Gi			
Gm			

where, indexes m=no. Of clusters/groups/classes as specified in classification problem

n=no. Of features as specified in classification problem.

3)Apply FCM method(self-organisng maps may be made use of or other clustering methods it outputs information about all "centers", membership values of each datapoint with respect to each of the centers.

These "centers" are cluster centers.

[C,u] = fcm(A , no. of groups);

Where,C=contains centers of clusters and each exist in real number space of dimensionality=(no. Of centers * (no. Of features+no. Of outputs (labelled as output1,output2...)));

C=

Centre	Feature 1	Feature n	Output 1	Output k
C1				
Cz				

If "A-Matrix" has no output columns then-

C=

Centre	Feature 1	Feature 2	Feature 3	Feature n
C1				
Cz				

Where,C=contains centers of clusters and each exist in real number space of dimensionality=(no. Of centers * no. Of features);

4) Replace each cell value of group-feature matrix (G), by the values in "center" matrix such that the most matching value in each column of "center" matrix with respect to each cell value in G.

:For each cell of "G-matrix"

Let me denote cell value in G for ith row jth column as G(i,j)

Now, search in column jth of "C-matrix" the most nearest matching/approximate

Value and replace the value in "G-matrix" for " G(i,j)" by value from "C-matrix" found by doing as above.

Repeat

3.1 Algorithm to update "G-matrix" and "Oumatrix" from values in "C-matrix".

For each column/feature of "G-matrix":indexed as "i"

For each row/groups/cluster/class of "Gmatrix":indexed as "j"

For each feature of "C-matrix":indexed as "m"

a(m)= absolutevalue(C(m,i)-G(j,i));

end;

minf=min(a(1:m));

gp_index=findindex(a(1:m)==minf);

 $G(j,i)=C(gp_index,i);$

end;

For each output column of "C-matrix":indexed as k from 1 to 1

If("A-matrix contains output columns")

Ou(j,k)=C(gp_index,no.of feature+k);

Else

Ou(j,k)=mean(G(j,:)+(max(G(j,:)min(G(j,:))/total.no of features

end;

comment—"Ou –matrix" is the matrix which holds the values for ouputs corresponding to each set of features for particular group as given for "G-matrix".

Result--Each cell of "G-matrix" is updated with the coordinate values of appropriate "centers" in such a way that value at each cell of "G-matrix" will represent a value describing the "center of attraction" for datapoint for particular group(say i) with respect to particular feature(say, j).

4."Algorithmic way to devise Rules of Inference for Fuzzy-classifier based on calculated statistical property value,which is indicated from the co-ordinates of "centers" in space Rno.of feature "

4.1 Design of Mamdani type fuzzy classifier ->

Take each feature of data and set it as inputs to the fuzzy classifier.

->Set type of fuzzy classifier as "Mamdani type".

->Set Universe of for each feature

--Calculate Min and Max values from the training set for each feature.

- --For each feature
- Set range as [Min Max]
- Or set range as [Min-somenumber between(0,1) *(Max-Min),Max + somenumber between(0,1) *(Max-Min)]; %so as be cautionary for future test data set and hence not to get out of bounds error.

->For each feature take as many membership functions as there are no. Of groups.

->For each feature's membership function set the type of MF's as either trimf,gaussf,gauss2f (depending on which gives better result under empirical study over training data set).

->set mean-value of each Membership Function's with that corresponding value in "G-matrix" for feature and for output MF's use values from "Ou-matrix".

->For each output/input

 Calculate distribution information of data in space for group by either adopting other neural techniques or by askng others so, as to know rough estimate on randomly selected large training set. (say, in case of fisheriris dataset each group has 33.3% share of data as given in data folder of this data set in "UCI" database)

• Take gaussmf(gauss2mf/trimf depending on satisfactory empirical results on training sets) to be in proportion to each of groups rough estimate of share of data with respect to range of 'Universe of discourse'[1][11] of each feature/output.

[consider, for a given dataset has associated 3-classes(A,B,C)

Class A contains "a"no. of datapoints; class B contains "b" no. of datapoints and Class C contains "C" no. Of datapoints .

Let range of any feature/output be say,"M"

Then, spread for each class say,

Sigma(A) for a particular feature/output=

a/m *(range of Universe of discourse);

];

• Set no. Of Membership functions of each output also same as no. Of group

4.2 Devise Rules of Inference

---no. Of rules =no. Of clusterers=no. Of groups;

->Take structure of "G-matrix" and "Ou-matrix" as reference.

(consider now only for single ouput case; you can generalise on your own time)

->For each row/group of "G-matrix"

• Construct Rule in the format as shown below

Consider "x " be the vector of input to the fuzzy controller.

Let vector x=[x(f1),x(f2).....x(f no.of features)];

Rule 1)--If x(f1) is gp1 and x(f2) is gp1 and x(f3) is gp1.... then o is gp1;

Rule i)--If x(f1) is gpi and x(f2) is gpi and x(f3) is gpi..... then o is gpi;

Now, fuzzy controller is ready to be used for classification.

Below is the flow-chart diagram of the above discussed algorithms created using Dia flow chart diagraming free and open-source software.



Fig 1: Flow-chart of the algorithms discussed above

Below are the screenshots of FIS GUI editor window(Fuzzy classifier) (MATLAB software) created after implementation of above discussed algorithms algorithms in MATLAB. In Rules editor GUI window where input values can be given at



Fig 2: Fuzzy classifier(FIS Editor)



Fig 3: Membership functions plots of first input

the lower left side and the result is seen over top-right side of this window.The result matches very closely to the values corresponding to each input.



Fig 4: Membership functions plots of second input



Fig 5: Membership functions plots of third input



Fig 6: Membership functions plots of fourth input

5. Conclusion

Tuning fuzzy classifier by above studied approach has lot of potential in classifying data points based on their inherent associative pattern. In addition, I strongly believe that using clustering methods with the above implementation of two algorithms, could help in finding distributive nature of signals and hence will enable estimation of proper time instants for sampling data signal and finally reconstruct exact continuous signals. Also, using Fuzzy controllers tuned with such clustering methods prove an helping hand in further providing knowledge of experience similar to that gained by "Great neural Network" (expert human). Hence, this above studied approach might open scope of using regression problems(say, reconstruction of entire continuos signal from discrete samples at discrete times) using fuzzy classifier is ample

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