

Cellular Automata based Degree Priority Routing Algorithm for Irregular Mesh Topology NOCs

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ABSTRACT

Irregular mesh topologies are used nowadays in NOCs due to the variation in the size & shape of IP modules integrated on a SOC. Irregular topology presents problems of routing, as each node may differ in their degree. Degree priority routing algorithms have already been proposed, which enables fast and dynamic routing. In this paper an improvement on the existing Degree priority routing (DPR) algorithm is proposed, by introducing Cellular Automata based neighborhood into the picture. The proposed technique enables each node to retain the degree information of its 4 neighbors (in a Cellular automata based Von Neumann neighborhood) and serves as a 'one node' hub to decide on the next best node to route the message to. This way a considerable amount of time is saved on DPR algorithms to route the message to the next best node with the optimal degree.

General Terms

Cellular automata, Irregular Mesh Routing algorithm

Keywords

Cellular automata, Von Neumann neighborhood, irregular mesh topology, Degree priority routing, XY routing algorithm.

1. INTRODUCTION

With the evolution of the VLSI technology more and more predefined components or IP modules are integrated on a single SOC (System on Chip). As number of modules increased, the traditional point to point and shared bus architecture proved inefficient. To bridge this gap, NOC (Network on chip) came into use. NOC is a highly structured and scalable solution to the deal with communication challenges on a SOC [4].

Topologies and switching mechanisms specify the architecture of a NOC. Topologies define the arrangement of IPs and their interconnection relationship. The switching mechanisms, on the other hand coordinates runtime traffic requests between sharing and conflicting resources to avoid deadlock [5]. There are numerous topologies that may apply to a NOC for efficient communication. Among them 2D Mesh is one of the simplest, point to point based topology that is popular nowadays. But with the growing variety of IP cores in shapes and sizes the 2D regular mesh is falling short of expectations. The problem is that with modules varying in dimensions the regular communication fabric is disrupted as

the network will now contain missing links. As a result of which the nodes of the network will have heterogeneous node degree, thus turning the 2D regular mesh to an irregular mesh. Now the basic XY or YX routing scheme which was initially meant for regular mesh topologies won't work on irregular mesh [3]. Thus modifications are made so as to adapt it to the irregular topologies. Degree priority routing is one of such improvements over the XY routing. In this approach the basic routing is dependent on the XY algorithm but also keeps the degree based priority of the nodes in view while deciding on the next hop node. In [3] the degree of a node is already known at that node and dynamic routing of messages are made to the next node with the optimal degree. Once the routing is made, the basic XY routing table is updated with the newly routed optimal paths.

This paper proposes some improvements over this existing approach. In the proposed algorithm the Degree priority routing is kept as it is but a new concept of Cellular Automata based neighborhood, is introduced. According to the algorithm each node will retain the degree values of four of its adjacent neighbors, (see figure 4) and compare and store them in order of decreasing degree. So each node will serve as a hub for routing to 4 (or less) of its neighbor nodes. In the previous approaches one had to go to each node to enquire about its degree and then take a routing decision. Thus with a one node hub concept proposed in this paper, the network latency is effectively reduced.

2. CELLULAR AUTOMATA (CA) & NEIGHBORHOOD.

To define it very simply, a cellular automaton is a kind of simple program [1], whose state changes depending on a certain predefined *rule*. CAs can be easily visually represented. The figure 1, explains the concept of CA rules and neighborhood. The horizontal row of cells marked 1, are the initial state of 3 cellular automata. Next state 2 shows the state transition of only the central cell. The two cells on both sides of the central cell are its adjacent neighbors. In other words these two cells act as the neighborhood of the central block. Now a cellular automaton's state changes

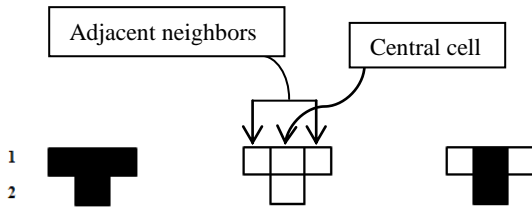


Fig 1: Basic Cellular Automata.

depending on a certain rule. These rules mainly involve the state of the automaton's neighbors. For the state change in the above diagrams the rule is as follows: *A cell should be black in all the cases where it or either of its neighbors was black in the step before* [1]. This neighborhood can be more complex, with increase in the number of adjacent neighbors. The two most popular CA neighborhoods are: Von Neumann neighborhood and Moore neighborhood.

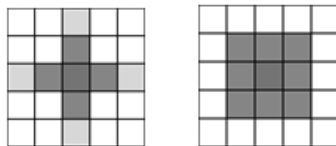


Fig2: CA Von Neumann & Moore neighborhood[7]

3. ROUTING ALGORITHM

3.1 XY routing algorithm

The classic XY[2] (static XY OR XY) routing algorithm which is a kind of distributed deterministic routing algorithm [6]. The XY routing algorithm compares the source node address (A_x, A_y) to the destination node address (B_x, B_y) of the packet, stored in the header information of data packet. Information must be routed to the core port of the node when the (A_x, A_y) address of the source node is equal to the (B_x, B_y) address. If this is not the case, the B_x address is firstly compared to the A_x (horizontal) address. Message will be routed to the East node when $A_x < B_x$, to West when $A_x > B_x$ and if $A_x = B_x$ the header information is already horizontally aligned. If this last condition is true, the B_y (vertical) address is compared to the A_y address. Message will be routed to South when $A_y < B_y$, to North when $A_y > B_y$. If the chosen node is busy, the header information as well as all subsequent information of this packet will be blocked. The routing request for this packet will remain active until a connection is established in some future execution of the procedure in this node.

3.2 Degree Priority routing algorithm

In [3] the term "degree" is defined as the number of output paths of node. This algorithm was proposed mainly for the irregular mesh architecture of NOC. Degree Priority routing algorithm is used to dynamically choose routing path with respect to the output channel of the next node. In this algorithm when source node or any intermediate node on optimal path wants to forward data packet towards the next node, it has to choose one node from number of neighboring nodes. In this mechanism it chooses the node having highest degree (i.e. highest number of available output paths) and forwards the packet. In this routing the routing table is been

maintained and any new optimal path hence generated dynamically are updated to the same.

3.3 Cellular Automata Neighborhood based Degree Priority Routing algorithm (CANDPR)

D_N : Degree of N^{th} node. See figure 4.

N: specifies the neighbor of the central node (C), as East (E) or West (W) or North (N) or South (S). Such that the degree of the East neighbor of central node (C) will be denoted as D_E , see figure 3.

$D_N(\text{max})$: maximum neighborhood degree among the 4 neighbors (East, west, North & South) of the central node.

N_N : The next hop node, e.g. N_E, N_W etc.

The proposed algorithm assumes that the basic "X-Y" routing algorithm, which is used in the case of regular mesh topology, is already in place. The routing is governed by compressed and constantly updated routing tables [3]. The CAN based DRP starts with the check that whether the destination node is within the scope or range. Range, here means that whether the destination node is among any of the 4 neighbors of the current node or central node (C). So if the destination node is anyone of the immediate neighbors then the message is directly routed to that neighbor and the cycle terminates.

In case the destination node is not in range (not in the immediate neighborhood) then the actual algorithm comes into action

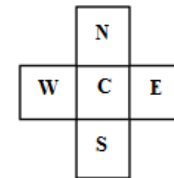


Fig3: A central node (C) and its neighborhood (East, West, North & South neighbors)

The central node (C) reads and stores the degrees of the nodes that fall into its Von-Neumann neighborhood, as shown in fig.1. Next the node compares all the degrees and stores them in a list of descending order. The node with the maximum degree is saved as $D_N(\text{max})$. Next it is checked that if the $D_N(\text{max})$ node is on optimal path.

An optimal path, is defined as [3] the path that belongs to XY or YX routing path, i.e. the best paths between the source and destination as possible in a regular mesh NOC.

So if the $D_N(\text{max})$ node is on optimal path then the algorithm directly opts for that node and the message is routed directly to that node. If the condition is not satisfied then another condition check is made. It is checked that if any node of the Von-Neumann neighborhood falls on the optimal path. If condition

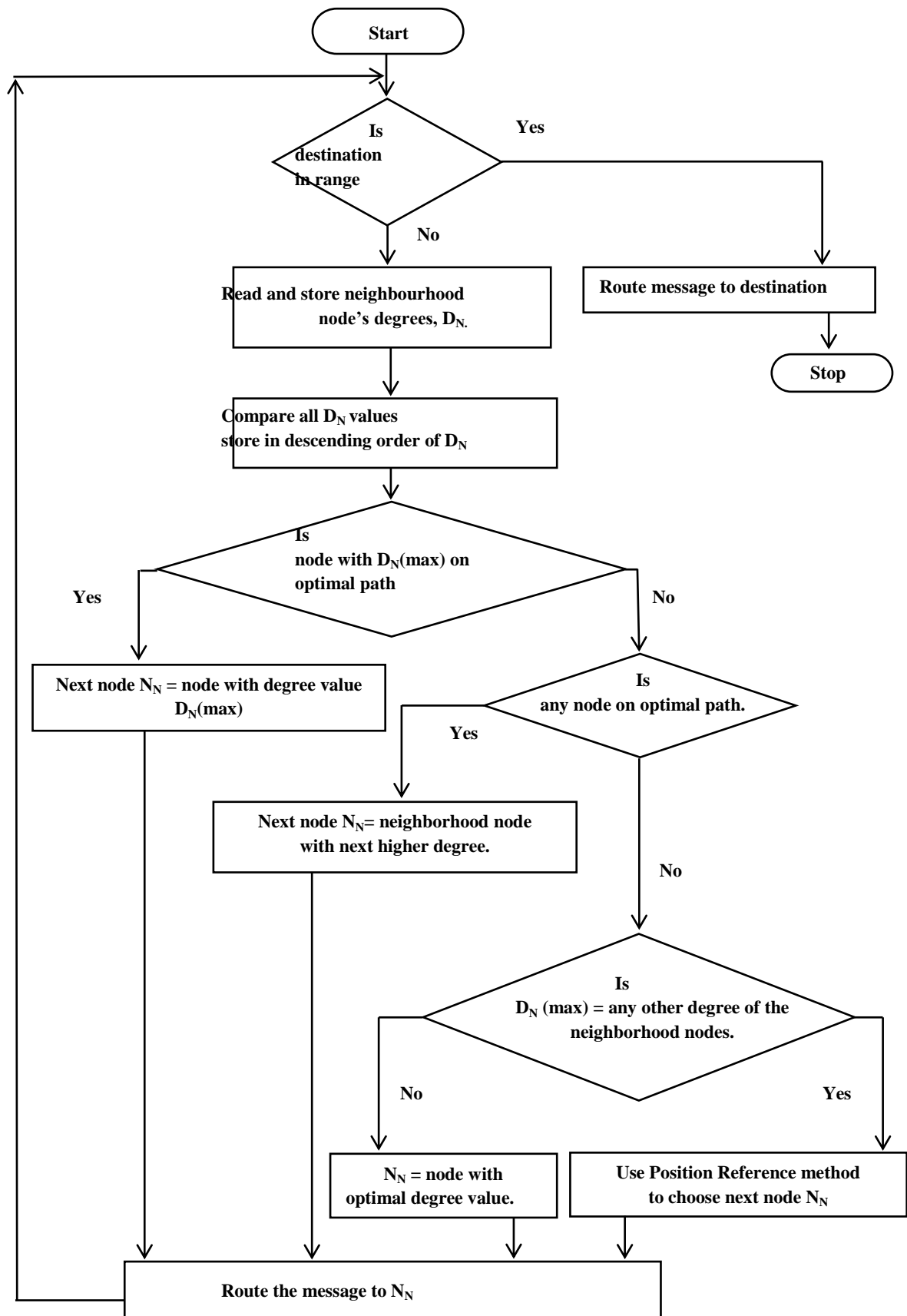


Fig 4: Flowchart of the algorithm

is satisfied then the node with the next higher degree is selected as the next hop node, and the message is directly routed as previous. If condition is not satisfied then another condition is checked. Here it is checked that if there are any redundant D_N (max) values. If the D_N (max) value is unique and no other node degree happens to be same to it, then the highest degree node or the node with degree D_N (max) is selected as the next node. Otherwise the “position reference method” is used, to decide on the next possible hop node. Next the message is forwarded as previously. Routing ends a phase of the cycle; then again the control is forwarded to 2nd step where the check is made about the destination.

3.3.1. Position Reference (PR) method.

This method is used when no node of the neighborhood is on the optimal path. In this situation nodes can be randomly selected for the next hop node, but it may lead to deadlock and other routing problems.

In this method, the relative positions of candidate node and the current node are checked, to see that if this candidate node provides a better position with respect to the destination. Here better position means that if the new node is at a position that is nearer to the destination, else that node (among the set of 4 nodes) whose position is nearer, is selected as the next node. The concept is explained in greater detail in example 4, of next section.

4. WORKING OF ALGORITHM

In the following 4 examples the possible routing methodology (that will be taken for routing a certain message from source to destination) is demonstrated. The methodology followed in these examples strongly adheres to the technique put forward in the text and diagrammatically represented in the flowchart. Each cell of the grid block (shown in figure 5 & figure 6) represents position of a router or switching node. Each large block in the same grid marked PE (processing element) represents the position of IP module of different size that are integrated on the SOC. The figures are for indicative purpose only and hence neglect the details of router to PE connectivity.

Ex.1, Source A – Destination E

In this case, since the node E is in the immediate neighborhood of A. Hence node A will pass on the packet to destination E directly.

Ex.2, Source A – Destination B

Since, node A and B are on optimal path, node A which already knows the node with optimal degree will route

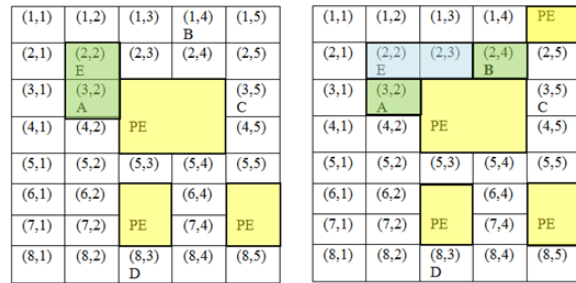


Fig 5: Examples 1 & 2.

message to E. In the next cycle E and B are also on the optimal path. Now, E will find highest degree node which is (2, 3) having degree of 3 and route message to it. Progressing in similar way the destination B(2,4) is reached.

Ex.3, Source A – Destination C

Since there is PE between node A and C creating obstruction on the optimal path, Node A has to dynamically route the message to the destination. Node A has 3 neighboring nodes of interest i.e. node E (2, 2), (3, 1) and (4, 2). Now node A will calculate and compare the degree of its neighboring nodes and since node E has the highest degree of 4, node A will route the packet to E. In the next cycle it is first checked that if E is on the optimal path, and since it is on the optimal path, message is forwarded through (2,3), (2,4), (2,5) finally to C(3,5).

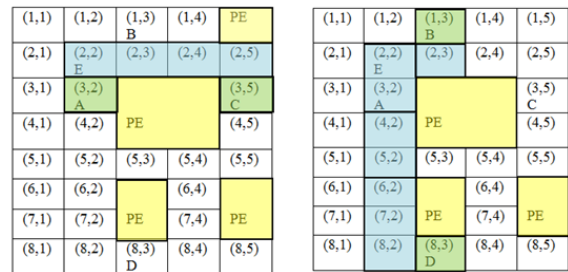


Fig 6: Examples 3 & 4.

Ex.4, Source B – Destination D

Since both nodes B and E are not on the optimal path, B will choose the node having the highest degree to pass on the packet. But the problem here is that there are 3 such nodes. Nodes (1,2), (2,3) and (1,4) have the same degree (=3) hence the PR method is used here to decide on the next hop node. In this method firstly the Y-coordinates of node D and nodes (1,2), (2,3) and (1,4) are compared, both (1,2) and (1,4) are in the same position vertically but node (2,3) is having less Y-coordinate difference than the other two nodes, node B will pass the packet to node (2,3). Now from (2,3) also there is no optimal path hence it will check for the highest degree

neighboring node i.e. E (2, 2) and will pass on the packet to it. The same thing is repeated with node (2, 2), since it is not on the optimal path. This process will carry on through nodes A, (4, 2), (5, 2). At (5, 2) again two nodes are having same degree and are not on optimal path. Hence it will select the node by PR method comparing Y coordinates of destination D with node (5, 4) and (6, 2). As the Y coordinate distance between (6,2) and D is less, it will select node (6,2) to pass on the packet and this way packet will finally reach to destination D through node (8,2).

5. EVALUATION

The proposed routing algorithm is evaluated on the basis of its network latency. Network latency is the amount of time taken by a data packet to traverse between the source and destination nodes of a network. Thus it is a very important parameter on which the efficiency of the network depends.

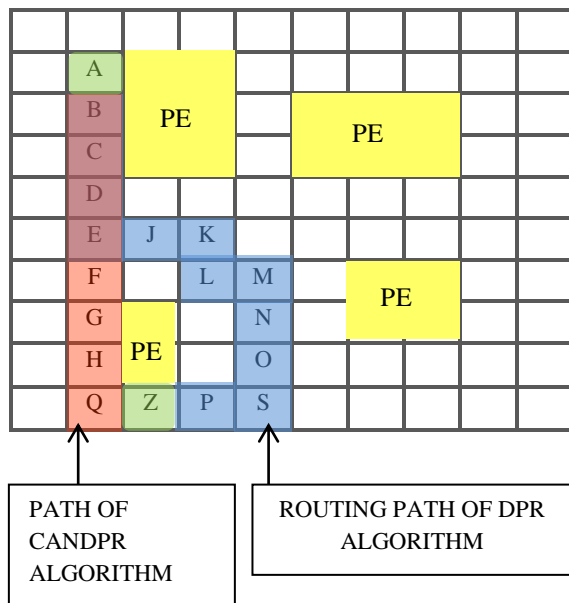


Fig 7: Comparison of DPR and CANDPR algorithms.

The comparison on network latency has been done on the same indicative grid like plan, representing routers and irregular IP blocks. Here in figure 7, node A is the source and node Z is the destination.

It is also assumed that 1 unit of time is consumed for forwarding a data packet from one node to the next.

As far as degree priority routing (DPR) algorithm is concerned, the message will be forwarded to a node whose degree is greater. In case if there are two nodes having same degree then it chooses the node having the highest degree. As shown in figure 7, above node A is the source node and node Z is the destination node for packet. Now according to both the DPR and the CANDPR proposed in

this paper, packet will go smoothly till node E, following the path through A-B-C-D-E.

But after node E, according to the DPR algorithm the packet will be sent to node J and not F. Though both of these nodes are having the same degree (= 4) but the next node of node J (node K) is having higher degree than the next node of node F (node G).

Hence according to DPR algorithm packet will travel via path A-B-C-D-J-K-L-M-N-O-S-P-Z travelling through 12 nodes and hence taking 12 unit of time. On other hand the proposed routing algorithm i.e. CANDPR will route the packet via A-B-C-D-E-F-G-Z travelling through 8 nodes and hence taking 8 unit of time. This contrast proves that CANDPR algorithm consumes less time to route the packets from source to destination and thus reduces the network latency.

6. CONCLUSION

The CANDPR algorithm proposed as a modification on DPR algorithm was compared and found to be effective in reducing network latency. This algorithm may work as well as fault tolerant routing algorithm as it can work around faulty nodes and missing links. Besides each node preserves the latest degree information about its neighborhood nodes hence it becomes easy and fast for the routing process to forward messages to the deserving node.

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