

# A Biometric Approach to Encrypt a File with the Help of Session Key

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## ABSTRACT

In this paper, we have employed “Face Recognition” technique with conventional session based authentication to provide a two layer security. Different features of a human face are used for authentication. Since this scheme uses biological characteristics, this is very difficult to forge. Additionally we will be using conventional session based authentication to provide a two layer security. This method of authentication can be used to grant access to a network, important files and documents.

The main objective of this work is to provide a two layer authentication system through biometric (face) and conventional session based password authentication. The encryption key for this authentication will be generated with the combination of the biometric key [7] and session based password.

## Keywords

Encryption, Decryption, Face Recognition, Biometrics, Genetic Crossover, Genetic Mutation, Evolutionary Algorithms.

## 1. INTRODUCTION

Network Security is an important feature in today’s computing world because of the following reasons:

- I. To ensure accountability [1], confidentiality [1], integrity [1], and above all protection [1] against many external and internal threats such as email based network security problems, denial of service network security attacks, worms and trojans, and wireless network security attacks.
- II. To monitor unauthorized access[1]

Face recognition [8] captures and analyzes the features of a human face like distance between eyeball, distance between nostrils, distance between lips, eyebrows, etc. These features of a human face remain identical irrespective of the circumstances.

The session based authentication uses a password, like a conventional authentication techniques. A key is generated using the password. Evolutionary operators like “Genetic Crossover” and “Genetic Mutation” are used to generate the key from the password. This key is used for encryption/decryption of the document(s).

The image of the individual must be taken in a closed environment. The environment used in the image for encryption must be same as that of the image used during decryption.

### 1.1 Genetic Crossover

This operator is generally used in evolutionary computing where the bits 0 and 1 store genetic information. In this type, a

single point is selected, and the strings are exchanged on either side of it. However, the generated offspring will definitely suffer if the selected site does not exchange the genetic information.[5]

Before crossover

String 1: 0100 | 011

String 2: 1101 | 111

After crossover

String 3: 0100 111

String 4: 1101 011

### 1.2 Genetic Mutation

According to the building block hypothesis, the order of genes is important. The purpose of mutation is to reorder the genes, in order to find chromosomes which have better evolutionary potential.[5] This mutation method simply changes (flips) a randomly selected bit:

Before mutation: 0111010101

After mutation: 0111000101

### 1.3 Image Processing

Image Processing is a form of signal processing for which the input is an image (photograph or frame). The image is treated as a two-dimensional image and the output of the image is either an image or a set of parameters or characteristics of the image. [13]

Image processing involves changing the nature of an image in order to either

- a. improve its pictorial information for human interpretation,
- b. render it more suitable for autonomous machine perception.

We shall be concerned with digital image processing, which involves using a computer to change the nature of a digital image. It is necessary to realize that these two aspects represent two separate but equally important aspects of image processing. A procedure which satisfies condition (a) - procedure which makes an image look better may be the very worst procedure for satisfying condition (b). Humans like their images to be sharp, clear and detailed; machines prefer their images to be simple and uncluttered.

## 1.4 Types of Images

When we click a photo from a camera, we get an image. This can be imagined as a two-dimensional function  $f(x, y)$ . We may assume that in such case image brightness can be in the range 0 (black) to 1 (white). It can take up any real values from 0 to 1. Digital image differs in such a way that all the  $f(x, y)$  values are discrete in nature. Each  $f(x, y)$  are integer numbers ranging from 0-256.[13]

Primarily, there are 4 different types of digital images:

- Binary [13]: Each pixel is just black or white. So, it needs only 1 bit for every pixel of the picture. The bit 0 indicates black and 1 indicates white.
- Greyscale [13]: Each pixel is a shadow of grey normally from 0 (from black) to 255 (to white).
- True Color or RGB [13]: Here each pixel has a color; that color being described by the amount of red, green and blue in it. If each of these components has a range from 0-255, then a total of  $255^3 = 16,777,216$  different colors. This is enough for any image. Since the total number of bits required for any image is 24, this is also known as 24-bit color image.
- Indexed [13]: Most color image have only a small subset of the more than 16 million possible colors. For the ease of file handling and storage the image has an associated color map or color palette, which is nothing but a list of colors used in that image. Each pixel has a value which does not give its color but is an index to the color to the map.

## 1.5 Aspects of Image Processing

It is convenient to subdivide the different image processing algorithms into following broad subclasses:

- Image Enhancement [13]: Processing of the image so that the result is more suitable for a particular application. Examples include:
  - Sharpening or de-blurring an out of focus image.
  - Highlighting edges.
  - Improving brightness of an image or the contrast
  - Eliminating noise
- Image Restoration [13]: This is reversing of the damages done to an image by a known cause. Examples include:
  - Removing of blur by linear motion
  - Removal of optical distortion
  - Removing of periodic interference
- Image Segmentation [13]: This involves subdividing an image into constituent parts or isolating certain aspects of an image:
  - Finding lines, circles or particular shapes in an image.
  - Identifying objects like cars, houses from an aerial image

We used edge filters [17] provided by MATLAB to pre-process an image. These filters implement edge detection algorithms. The important filters are as follows:

## 1.6 Sobel Filter

Sobel operator calculates the gradient of the image intensity at each point, giving the direction of the largest possible increase from light to dark and the rate of change in that direction. The result therefore shows how "abruptly" or "smoothly" the image changes at that point and therefore how likely it is that that part of the image represents an edge. Mathematically, the operator uses two  $3 \times 3$  kernels which are convolved with the original image to calculate approximations of the derivatives - one for horizontal changes, and one for vertical. [17]

If we define  $A$  as the source image, and  $G_x$  and  $G_y$  are two images which at each point contain the horizontal and vertical derivative approximations, the computations are as follows:

$$G_x = \begin{bmatrix} -1 & 0 & +1 \\ -2 & 0 & +2 \\ -1 & 0 & +1 \end{bmatrix} * A$$

and

$$G_y = \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ +1 & +2 & +1 \end{bmatrix} * A$$

Here,  $*$  here denotes the 2-dimensional convolution operation.

## 1.7 Prewitt Filter

The Prewitt operator is used in image processing, particularly within edge detection algorithms. Technically, it is a discrete differentiation operator, computing an approximation of the gradient of the image intensity function. At each point in the image, the result of the Prewitt operator is either the corresponding gradient vector or the norm of this vector. Mathematically, the operator uses two  $3 \times 3$  kernels which are convolved with the original image to calculate approximations of the derivatives - one for horizontal changes, and one for vertical. If we define  $A$  as the source image and  $G_x$  and  $G_y$  are two images which at each point contain the horizontal and vertical derivative approximations, the latter are computed as:

$$G_x = \begin{bmatrix} -1 & 0 & +1 \\ -1 & 0 & +1 \\ -1 & 0 & +1 \end{bmatrix} * A$$

and

$$G_y = \begin{bmatrix} -1 & -1 & -1 \\ 0 & 0 & 0 \\ +1 & +1 & +1 \end{bmatrix} * A$$

Here,  $*$  here denotes the 2-dimensional convolution operation.

## 1.8 Roberts Cross

The Roberts' Cross operator is used in image processing and computer vision for edge detection. It was one of the first edge detectors and was initially proposed by Lawrence Roberts in 1963. As a differential operator, the idea behind the Robert's Cross operator is to approximate the gradient of an image through discrete differentiation. According to Roberts, an edge detector should have the following properties: the produced edges should be well-defined, the background should contribute as little noise as possible, and the intensity of edges should correspond as close as possible to what a human would perceive. [17] With these

criteria in mind and based on then prevailing psychophysical theory Roberts proposed the following equations:

$$y_{i,j} = \sqrt{x_{i,j}}$$

$$z_{i,j} = \sqrt{(x_{i,j} - y_{i+1,j+1})^2 + (y_{i+1,j} - y_{i,j+1})^2}$$

where x is the initial intensity value in the image, z is the computed derivative and i,j represent the location in the image.

In order to perform edge detection with the Roberts operator we first convolve the original image, with the following two kernels:

$$\begin{bmatrix} +1 & 0 \\ 0 & -1 \end{bmatrix} \text{ and } \begin{bmatrix} 0 & +1 \\ -1 & 0 \end{bmatrix}$$

## 2. PROPOSED ALGORITHM

Following are the main steps of the Encryption algorithm:

### A. Biometric Key Generation

#### Step 1: Image Acquisition

#### Step 2: Pre-processing of the Image

#### Step 3: Feature Extraction

#### Step 4: Biometric Key Generation from the Average Threshold Feature

#### B. Session Key Generation

#### C. Combine the Biometric Key with the Session Key

#### D. Encryption of the Document using the Key

Following are the main steps of the Decryption algorithm:

#### A. Biometric Key Generation

#### Step 1: Image Acquisition

#### Step 2: Pre-processing of the Image

#### Step 3: Feature Extraction

#### Step 4: Biometric Key Generation from the Average Threshold Feature

#### B. Session Key Generation

#### C. Combine the Biometric Key with the Session Key

#### D. Decryption of the Document using the Key

The basic flowchart of the algorithms is shown below:

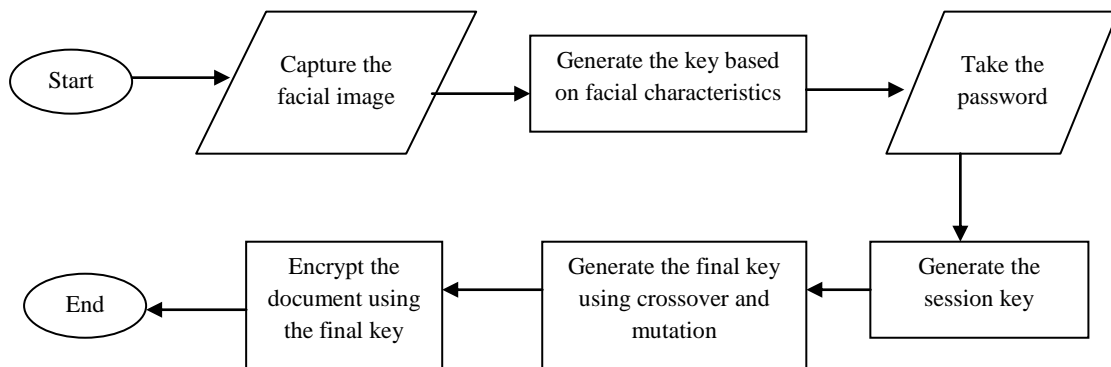


Figure 1: Flowchart for encryption

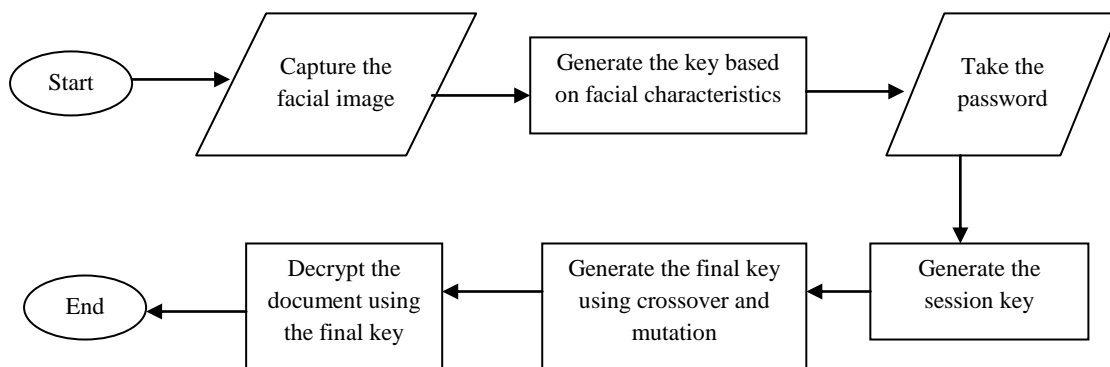


Figure 2: Flowchart for decryption

### 3. EXPLANATION OF THE ALGORITHM

#### 3.1 Image Acquisition and Pre-processing

Step 1: Use a camera to capture the face image.

Step 2: The image is pre-processed to capture the minimum face area and then the feature points are extracted.

#### 3.2 Encryption/Decryption Key Generation

This process consists of the following steps:

##### A. Biometric Key Generation

Step 1: From the feature points of the face, average biometric value is generated. In this paper feature points are taken as distance between two eyes, nose trails, lip-ends, eyebrows.

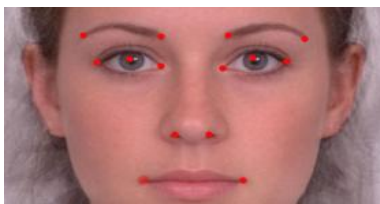


Figure 3: Feature points of the face

Step 2: From a number of sample images, different average values are generated.

Step 3: With this, we generate an upper and lower threshold value minimizing the FAR and FRR.

Step 4: The test face image is verified, if the average value lies within range we accept it and then generate a biometric key, say  $k_1$  of 24 bits.

##### Session Key Generation

Step 1: Take the user password as input from the user.

Step 2: The password should be at least 6 characters.

Step 3: Read the password and generate 8 bit binary number, say  $k_2$ .

Step 4: Generate a number, say  $n$ , within the range of 3 to 5 from  $k_2$  using modulo 6 operation.

##### B. Final key Generation

This consists of two steps:

###### a. Genetic Crossover Process

Step 1: Divide  $k_1$  into 2 parts of length  $(2*n)$  and  $(24-(2*n))$ . We call the substrings as  $keystr1$  and  $keystr2$  respectively.

Step 2: Divide  $k_2$  into 2 parts of length  $(n)$  and  $(8-n)$ . We call the substrings as  $keystr3$  and  $keystr4$  respectively.

Step 3: We used the 4 substrings for genetic crossover to obtain an intermediate final key, say  $k$

###### b. Genetic Mutation Process

Step 1: Flip the bits of  $k$  at  $n$  bit position and multiple of  $n$  bit position (upto 32 bits) to obtain the final key (say  $fk$ ).

#### 3.3 Encrypt the Document using Final key

Step 1: Divide the binarized document text file of size  $m$  into  $m/32$  segments and store them in matrix  $T$ .

Step 2: Encrypt each module with the final key  $fk$ .

Step 3: Flip the remaining  $m\%32$  bits.

Step 4: Take a transpose of matrix  $T$  to  $T1$ .

A schematic diagram of the encryption process is shown below:

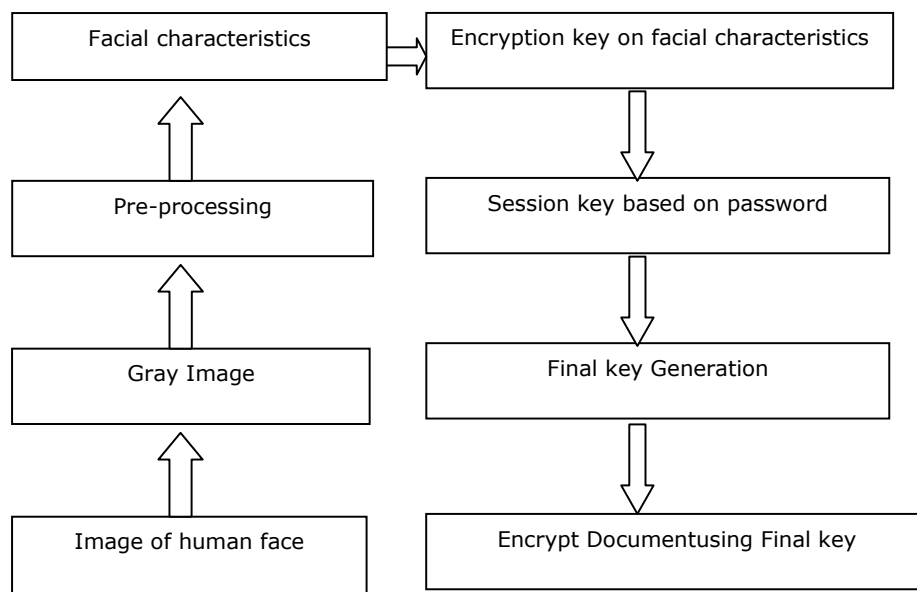


Figure 4: Schematic Diagram for the encryption process

### 3.4 Decrypt the Document using Final key

Step 1: Read and store the encrypted file in a matrix T.

Step 2: Take a transpose of matrix T to T1.

Step 3: Flip the remaining  $m\%32$  bits.

Step 4: Decrypt each module with the final key fk.

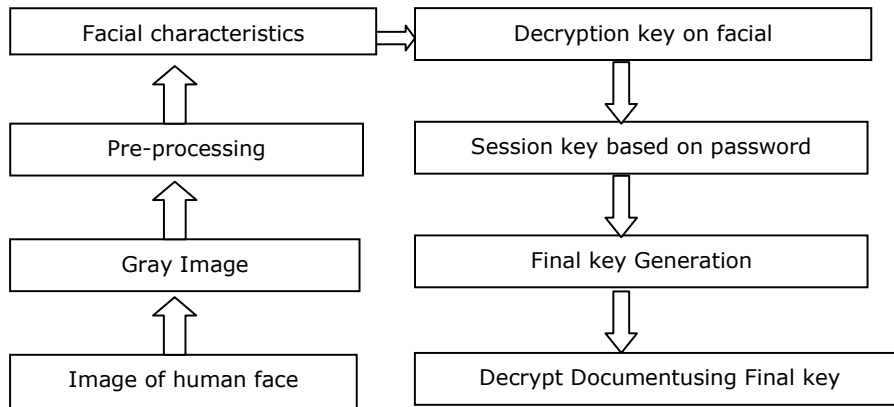


Figure 5: Schematic Diagram for the decryption process

## 4. RESULTS AND DISCUSSIONS

In this section we present the experimental results of the proposed approach which was implemented in MATLAB 7.0



Figure 6: Main Menu

The original image as captured by the camera is shown in figure 7.



Figure 7: Original image

In figure 8, we show the image after applying the image processing filters. All the biometric features are derived from the below image.

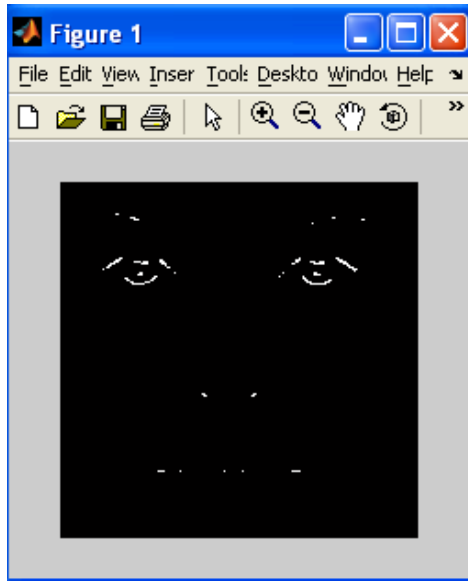


Figure 8: Intermediate image extracted from original image

Figure 9 shows a sample file before encryption.

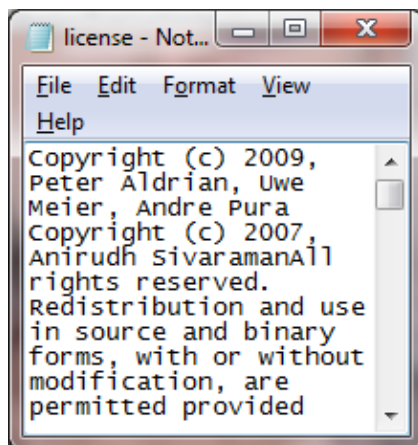


Figure 9: Original File before Encryption

Figure 10 shows the file after encryption with biometric and genetic operators.

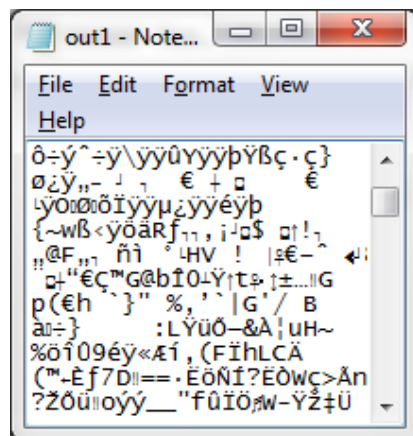


Figure 10: Encrypted File

## 5. CONCLUSION

The proposed approach provides two layer security. Encryption is symmetric. Using evolutionary concepts like crossover and mutation provide better security. This coupled with biometric security makes things very secure. The feature points which we have used are relative for example, distance between eyeballs, distance between nostrils and distance between the end points of the lips. So, these feature points are rotation (of the face) independent. The proposed approach may be further extended using more reliable and costly biometric features like retina, iris, palm print etc and also by increasing the number of bits for biometric key. The method described above is a cost effective method of encryption suitable for small and middle level organizations.

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