

Environmental Scrutinizing System based on Soft Computing Technique

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ABSTRACT

Artificial intelligent techniques are very much needed to design the environmental monitoring systems. These systems must be smart enough so that all the decisions taken by the system must be accurate. Soft Computing (SC) it is a set of computational methods that attempt to determine satisfactory approximate solutions to find a model for real-world problems. It based on various techniques such as Artificial Neural Networks, Fuzzy Logic and Genetic Algorithms. The aim of this paper is to implement a soft computing technique which is artificial neural network based on Self-Organizing Feature Map (SOFM). SOFM model for monitoring and collecting of the data are real-time and static datasets acquired through pollution monitoring sensors and stations. In the environmental monitoring systems the ultimate requirement is to establish controls for the sensor based data acquisition systems and need interactive and dynamic reporting services. SOFM techniques are used for data analysis and processing. The processed data is used for control system which even feeds to the alarming systems.

General Terms

Soft Computing, Environment, Software System

Keywords

Environmental modeling, EMS, air pollution, environmental sensors, Self-Organizing feature Map

1. INTRODUCTION

There will be a positive impact on the standard of living through improving the smart environmental management and monitoring services. Pollutants are increasing in the environment and monitoring the pollutants and bringing into control is the major challenge. Information technology and computing has a major role in the current situation. Moreover, this research assisted in building a collaborative framework that is able to connect the proposed framework to international environment management systems, in order to gain experiences from high profile specialist environmentalists around the world.

Gaining such knowledge and experience from specialists in the field has cost effective implications for people. Moreover, this paper focused on building intellectual capacity in the fields of environmental informatics; in this field has a pronounced shortage at the present time. The proposed system and framework is a generic model that manages monitors and provide alerts on the emissions of the air pollutants, which can be applied anywhere in the world and

any region, and is able to manipulate the data that is received from any type of sources [3].

A pilot project for monitoring the air pollution at Sohar Industrial Zone is developed in collaboration with the Sohar Environmental Unit (SEU), a separate agency promoted by Ministries which are responsible for all environmental monitoring and management within the entire industrial zone.

Sensor technology and Nano technology with information technology is building the solid base for the environmental informatics.

The project offers a complete decision-making system that is able to analyze the gathering data from remote sensors. In addition, building a national benchmarking system is one of the outcomes of this research. The benchmarking system will be used to produce based on MECA's policies and regulations.

The benchmarking system takes into consideration the nature of the industry. The proposed system and framework suggest a generic model that is able to manage, monitor and provide alerts on the emissions of the air pollutants, which can be applied anywhere in the region where the source of pollutants are there. As a part of this project; a case study of the feasibility of using this framework is conducted, to focus on establishing a smart monitoring system for air pollution. This is done in collaboration with SEU and University of Queensland, Australia. Moreover, as part of this research, awareness among local community will be developed towards environment pollution, and to take seriously their responsibilities towards the environment. This will be done through conducting environmental workshops and outreach sessions [18].

Technology transfer is another focus of the project through adopting the latest technologies in environment monitoring systems. Furthermore, in this paper an attempt is made to merge knowledge management techniques with e-environment systems applications. This has been suggested in order to generate a generic model for environmental monitoring system to monitor the emissions of air pollutants, especially in the industrial regions [2].

2. POTENTIAL BENEFITS FROM ENVIRONMENTAL MONITORING

- Materials savings from more complete processing, substitution, re-use or recycling of product inputs
- Increases in process yields

- Less downtime through more careful monitoring and maintenance
- Reduced material storage and handling costs
- Savings from safer workplace conditions
- Reduction of costs associated with emissions, discharges, waste handling, transport & disposal
- Improvements in the product as a result of process changes
- Higher quality, more consistent products
- Lower product costs (e.g. from material substitution)
- More efficient resource use
- Higher product re-sale and scrap value

3. CYBER INFRASTRUCTURE FRAMEWORKS

Multi-Agent Systems [9] is used in smart monitoring simulators and intelligent systems to perform several tasks like

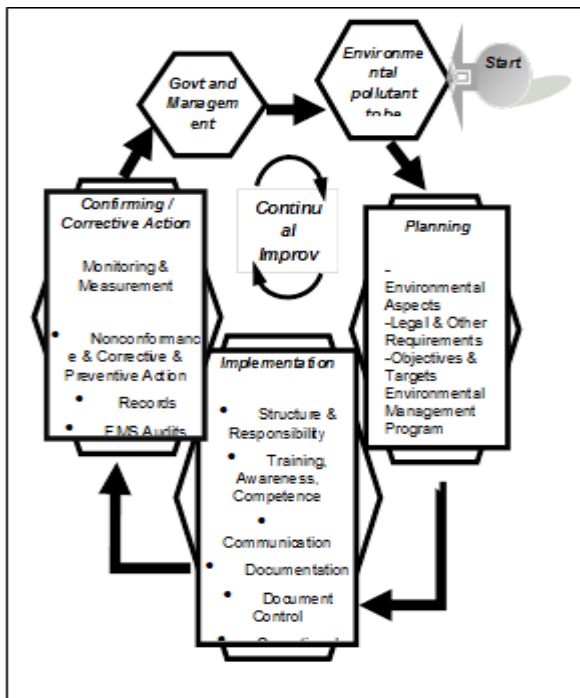


Figure1. Cyber Framework

data filtering and alarming systems. Agents have to react to events, define strategies, interact, and participate in the activities of the system as shown in Figure 1. Internet is also busting use for such agent based systems.

4. DATA QUALITY

Data quality and accuracy remain a major challenge for researchers and organizations. Over time techniques and procedures have evolved designed to make sure data quality meets certain standards [10].

Data and information are very dynamic which present the following issues, like data gathering, data delivery, destruction due to inappropriate pre-processing, data integration [16].

4.1 Poor Data Quality Impact

Poor data quality management in environmental data can lead to the following which includes Lowered end user satisfaction of an EMS. Poor data quality increases cost due to the fact that time and money will be spent in detecting and correcting errors rather than performing critical operational tasks. It is a fact that the decision made is no better than the data it was based on. Therefore, poor data quality will lead to poor decision making which lead to incorrect estimate and predictions. E-environment is so sensitive that we should not tolerate any compromise when it comes to decision making or we will endanger people and planet earth. More difficult to set strategy and execute it. Environmental strategic decision requires data gathering from various data sources with some uncertain quality. This makes it harder to develop a sound strategic decision. Executing the strategy becomes difficult as inaccurate results become evident [6, 7].

4.2 Cleansing Of Environmental Data

Current data collected by SEU are not hosted in centralized warehouses rather it's saved in Excel spreadsheets. This presents an issue with data cleansing and integration between distributed sensors. Data cleansing is required when integrating data from distributed sensors. In order to clean the data they need to be integrated using the appropriate methods. Here an attempt is made to execute a method for integrating multiple data sources from different environmental sensors

4.3 Multi-Source Problems

Data collected from different environmental sensors can present a large data cleansing issue when integrated. This is due to the fact that data quality problems will be inherited from the source databases. Environmental data sources typically developed deployed and maintained independently to serve specific needs [13]. By looking at Sohar industrial region environmental data we can observe the multi-source cleansing problem.

One major issue when cleaning data from multiple sources is how to identify overlapping records. Any duplicate information should be purged out and complement information should be consolidated and merged in order to have a consistent and accurate reflection for the real world entity [17]. AS example if two records were found duplicate we are going to merge them and add the sensor Id from each record. This act as a historical reference in case we need to infer some information in the future [1, 15]

Some records has different date format, apply the same date format for the date column mm/dd/yyyy as follows:

If we have the following:

Sensor1 (Date= 29/02/08, time =0:00)

Sensor 2(Date=02/29/08 time=24:00)

Then we first sort date and time field. Then check date before and after the suspected date column in the data sources. If the date after that record is exactly the same as the other record then we know that the previous date is duplicated.

5 NEURAL NETWORKS MODELING

Artificial Neural Networks (ANN) is considered as a new paradigm in computing, embodying a view of computation inspired by the brain biology [11]. Neural networks are a powerful tool capable of learning and dissemination of data which is the way to model the data, both linear and nonlinear [12]. Neural networks have certain advantages have stimulated researchers to the adoption of neural networks as a tool to calculate the variables in the systems and issues that do not have available the large amount of data or that require unusual methods of calculation. The main characteristics are Massive parallelism, Uniformity, ability of learning, ability of Training, ability of generalization, and adaptivity [11]. Most applications of neural networks realize into prediction, classification, data association, data conceptualization and data filtering [4].

The neuron is the processing unit which takes number of values as inputs and producing an individual output. The neurons are of three types input, hidden and output layers. The input layer is does not consist of a transfer function [11]. SOM normally is used in unsupervised learning approaches using of the concept of feature maps. The input of high-dimensional data can be mapped on a two-dimensional map called the feature map. Each node in the SOM represents some point in the input space.

The main concept in the SOM learning process is that the winner nodes and its neighborhood are changed closer in the input data space. The Hebbian rule is used in modification of weights. The adjustment of the activity has an effect on the neighboring neurons; therefore, if we adjust a neuron, we would also be adjusting its neighbors. The input in the OSM can be described as

$$Y = [y_1, y_2, y_3, \dots, y_n]^T$$

In which $y_1, y_2, y_3, \dots, y_n$ represents the selected features, and the synaptic weighting vector for j_{th} neuron is denoted by

$W_j [w_{j1}, w_{j2}, w_{j3}, \dots, w_{jn}]^T, j = 1, 2, \dots, m$. Where m is the number of the neuron.

The distance between the feature vector and weighting vector can be expressed as

$$d_j = \|Y - W_j\|, j = 1, 2, \dots, m.$$

The winning neuron q is the minimization of expression and, and can be expressed as

$$d_q = \min_{A_j}(d_j)$$

The feature map is considered as the most important concept introduced by SOM networks. The training of SOM involves mapping up of the highly dimensional input space into two-dimensional feature maps. The Mapping of data refers to giving a 2-dimensional demonstration with a finite size to the input space.

An illustration of Self-Organizing Feature Map Neural Network is depicted in Figure 2.

The architecture of neural network is the organization of neurons into layers and the connection pattern between them, it demonstrated as follows: 'R-S1-S2-S3', which means the input layer consists of R values. And it has two hidden layers referred as $S1$ and $S2$. The output layer is referred as $S3$ neurons. The transfer function of each neuron must define for all layers in the network. Besides, the weight values for each neuron should also define. The training process is the

adjustment of weights of the NN to 'match' set of samples (training set). For the sake of network generalization, the 'match' of training sets enables us to infer from unseen samples.

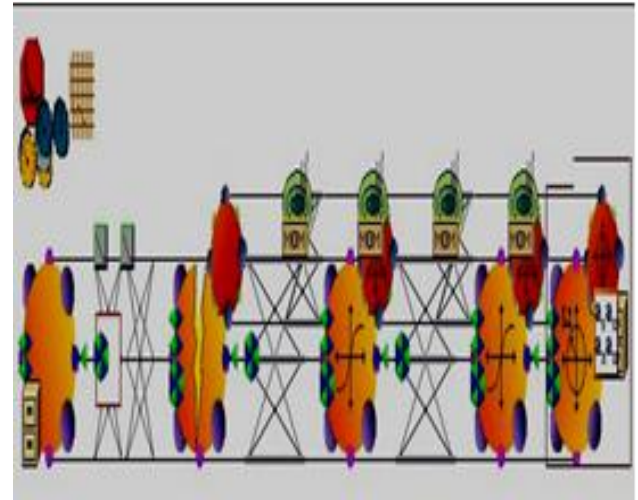


Figure 2: Self-Organizing Feature Map Architecture

Before using the neural network, we need to encode the input text into a suitable form. The data set must divide into three categories; training data sets cross validation data sets and test data sets. The Cross validation computes the error in a test data sets at the same time that the network is being trained with the training set.

To develop the SOM model for environment monitoring system, a training process was first conducted to determine the model parameters. This process used the input vectors of the frequency domain training feature to modify the weighting vector

And

create a final weighting vector for each winning neuron for the corresponding feature vector

6 EXPERIMENTS AND RESULTS

The experiments covered five gases CO, CH₄, H₂S, SO₂ and O₃, the input file is encoded into a suitable form and then divided it into three categories; training data sets cross validation data sets and test data sets. The Cross validation computes the error in a test data sets at the same time that the network is being trained with the training set.

6.1. Implementation of the Proposed Systems

The experiments are implementing using the NeuroSolution packages to design the SOMF which has 25 PEs for input and 25 PEs for output layers respectively. The SOMF Network has only one hidden layer. Basically, the size of the Kohonen layer must be maintained as small as possible because the SOMF trains slowly. The Starting and Final Radius are 2, 0 respectively. The data will map on 5 by 5 dimensional feature maps. Every PE has an adaptive parameter which it must change according to some pre-specified procedure. The Back propagation learning technique is used as a learning approach in neural network. The weights are changed based on their previous value and a correction term.

The learning rule is the means by which the correction term is specified. The momentum component is used as learning rule.

The step size is 1 and the momentum rate is 0.7. The Genetic optimization is used to find the best values for these parameters [21, 22] .

There is several ways to test the networks performance. Usually, MSE "mean squared error" is used. It is two times the average cost which is computed as follows:

Where, P is the number of output processing elements. N is the number of exemplars in the data set. y_{ij} is the network output for exemplar i at processing element j . d_{ij} is the desired output for exemplar i at processing element j .

Final MSE of CH4 is 0.000506334at epoch 999 at run 3, and the correlation between the desired output and actual network output is 0.999081896. The average of MSE with standard deviation boundaries for 3 runs of CH4 shows the training and cross validation graph is clearly smoothly trained and they are closely to each other from the epoch 25, and the network is smoothly trained as shown in Figure 3 and results summarize in table1.

Table 1 the best SOMF results for CH4

<i>Best Networks</i>	<i>Training</i>	<i>Cross Validation</i>
Run #	3	3
Epoch #	999	999
Minimum MSE	0.000506334	0.000713675
Final MSE	0.000506334	0.000713675

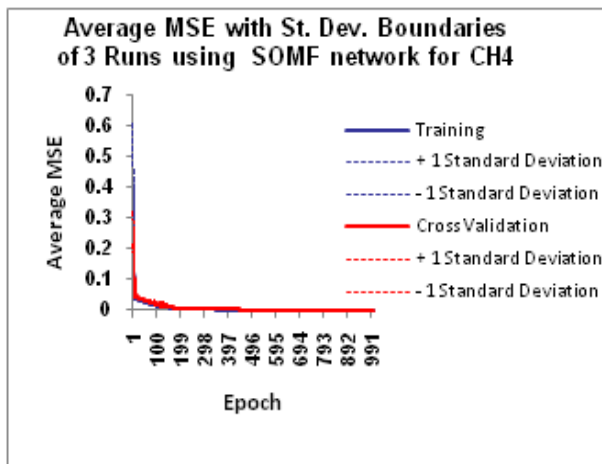


Figure 3: average of MSE with standard deviation boundaries for 3 runs of CH4

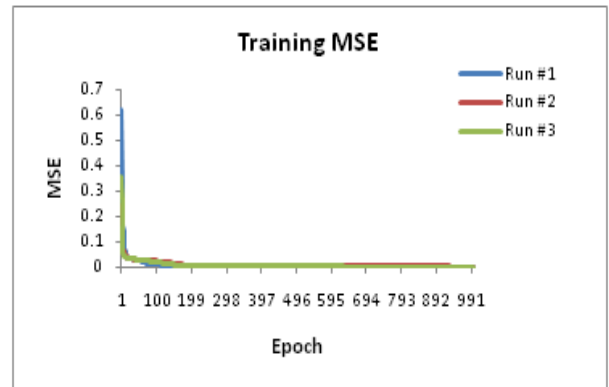


Figure 4: average of MSE of training data set for 3 runs of CH4

Figure 4 depicts the final MSE value for tree run of training data set for the sake of testing the stability of network and then the generalization process. And Figure 5 illustrates the final MSE value for tree run of cross validation data set for the sake of assessing the generalization of the proposed model by the analysis of accuracy of the model predictions on seemingly independent dataset.

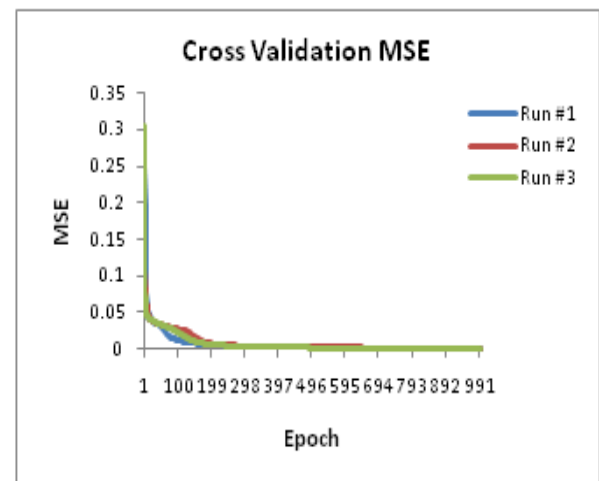


Figure 5: average of MSE of cross validation for 3 runs of CH4

6.2. Comparison of Results with other Researcher

Some researchers are using the concept of sensor arrays and pattern recognition which applied to the obtained signal patterns for environmental monitoring but this approach is not suitable for giving the exact information about concentrations of individual species [23]. In our work we are addressing the individual gases concentration with time and date.

Portable systems are very accurate in predicting and identifying the pollutants and contaminants in the environment. Technological advancement in the field of sensors and Nano technology helps in environmental restoration and handling the waste management. There are prototyping sensing systems are developed which are having sensing elements, data acquisition system, computer, and neural network implemented in software and are capable of automatically identifying pollutants. Various gas sensors like tin oxide gas sensors can be used to identify various chemical vapors. In Optical sensors array is also used in identifying the chemical dyes in liquids. Some systems use portable gamma

ray spectrometer to identify radioactive isotopes. Neural network is used to identify the composition of the sensed pollutants. With intense training in the neural network computation is carried out for propagation of data through the network. The computation involved during operation consists of vector-matrix multiplication and application of look-up tables (activation function), unknown samples can be rapidly identified in the field

7 ALERT SYSTEMS

Air pollution is a serious problem that can lead to catastrophic outcomes if not managed and controlled properly. Atmosphere has a complex mixture of airborne particles with varying sizes coming from different sources which need to be monitored and controlled. Artificial intelligence Self-Organizing Feature Map (SOFM) is implemented and proposed for designing an alert system for the pollution control and monitoring. Our network can appropriately predict the exact values of gases which are responsible for the pollutant. The PM presence and dispersion in the atmosphere depends on a wide range of factors including meteorological. Data gathered from different environmental sensors needs to be analyzed and assessed appropriately. For any system that handle critical data that can reduce catastrophic impact on the population has to be credible and effective. Credibility demands that the system is accurate when dispatching a red alarm signal. The system will need to calculate the concentration of PM in a distributed area taking into accounts many external elements such as Temperature, wind, wind speed, rain storm and dust storm [14]. The system has to be smart enough to issue an early warning based on area of effect and the degree of impact. When **cyclone Gunu** [5] hit Oman many havoc was everywhere. Although a warning was issued by the government earlier but still there was losses of life and destruction. This raises a few questions, regarding the alarming process employed. Similarly a big lesson was learned from tsunami the problem wasn't the forecasting rather it was the alarming system. For any effective alarming system it must be credible and functional under catastrophic conditions. In case of air pollution control system if any particular gas rations increase, the alarming system will notify the controller and will send warning.

8 CONCLUSIONS

In this paper we developed a framework and set of services to enable streamlined access to a collection of real-time, near-real-time and static datasets acquired through pollution monitoring sensors and stations. We proposed pollution control management system and Web Portal to enable the sharing and integration of the high quality data and models for pollution control resource managers. Data cleaning is implemented in this paper and artificial intelligence techniques are implemented to train the collected data set. Artificial intelligence technique ANN (Self-Organizing Feature Map) is used for data analysis and this processed data is used for developing alarming system [19].

9 FUTURE RESEARCH WORK

The practical test bench needs to be verified and tested in the real world situations. This system is life critical so before release the reliability must be tested correctly. There are other

soft computing techniques like genetic algorithms, and fuzzy which can be implemented for the sake of optimization of the results [20].

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