# A Note on a Theorem for Two pairs of Weakly Commuting Maps

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## ABSTRACT

Major corrections are suggested to a theorem of Joshi and Mehta (2010) for two pairs of weakly commuting self-maps on a complete metric space.

## **Keywords**

Complete metric space, implicit relation, Weakly Commuting self-maps, and common fixed point.

## **1. INTRODUCTION**

Let X be a metric space with metric d. If  $x \in X$  and f is a self-map on X, the f-image of x and the range of f are denoted by fx and f(X) respectively. Also Sf denotes the composition of self-maps S and f on X.

Self-maps *S* and *f* on *X* are commuting fS = Sf. Sessa [1] introduced a weaker condition of commutativity as given below:

**Definition 1.1** Self-maps *S* and *f* on *X* are *weakly commuting* if  $d(Sfx, fSx) \le d(Sx, fx)$  for all  $x \in X$ .

Obviously every commuting pair is weakly commuting. But the converse is not true as seen in [1] and [2].

This was further generalized by Jungck [3].

**Definition 1.2** Self-maps S and f on X are *compatible* 

if  $\lim_{n \to \infty} d(Sfx_n, fSx_n) = 0$  whenever there is  $a \langle x_n \rangle_{n=1}^{\infty} \subset X$ such that

$$\lim_{n \to \infty} fx_n = \lim_{n \to \infty} Sx_n = t \text{ for some } t \in X. \qquad \dots \qquad (1)$$

A compatible pair need not be weakly commuting one [3]. One can refer to [4], [5], [6] etc. for nice works related to compatibility.

**Remark 1.1** Non-vacuously compatible self-maps which ensure the existence of sequence  $\langle x_n \rangle_{n=1}^{\infty}$  in *X* with choice (3) commute at their coincidence points.

Self-maps which commute at their coincidence points are called weakly compatible maps [7]. Further study of weakly compatible maps can be found in [8],[9], [10], [11], [12] etc.

The following was mentioned as Proposition 2.1 in [13]:

**Lemma:** Let (S, f) be compatible pair self-maps on a metric space X where f is continuous. Then the pair is weakly compatible.

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The continuity of *f* is not necessary indeed to obtain the conclusion of the lemma. In fact, writing  $x_n = x$  for all *n* in Definition 1.2, it follows that Sfx = fSx whenever fx = Sx. In other words *S* and *f* are weakly compatible.

It may also be noted that the lemma plays no role in proving their main theorem.

Let  $F^*$  be the class of real valued non-negative functions  $F:[0,\infty)^5 \rightarrow [0,\infty)$  with the following choice:

- (F1) *F* is non-decreasing in its fourth and fifth coordinate variables
- (F2) there exists  $h \in \Box[0,1)$  such that for every  $u \ge 0$ ,  $v \ge \Box 0$

 $u \le \max\{F(v, v, u, u + v, 0), F(v, u, v, u + v, 0)\} \Longrightarrow u \le hv.$ 

(F3) If  $u \le \max\{F(u,0,0,u,u), F(0,u,0,0,u), F(0,0,u,u,0)\},\$ then u = 0.

The result of Joshi and Mehta [13] is

**Theorem 1.** *Let S, T, f and g be self-maps on a complete metric space X such that* 

$$S(X) \subset g(X)$$
 and  $T(X) \subset f(X)$  ... (2)

and satisfy the inequality:

$$d(Sx,Ty) \le F(d(fx,gy), d(fx,Sx), d(gy,Ty), d(fx,Ty), d(Sx,gy))$$
  
for all  $x, y \in X$ , ... (3)

Then S, T, f and g have a unique common fixed point z in X. Further z is a unique common fixed point of the pairs (S, f) and (T,g).

The statement of Theorem 1 is incomplete in its present form and requires some additional conditions. Based on some meticulous observations, in the next section major corrections are suggested to Theorem 1 and is restated appropriately.

## 2. OBSERVATIONS AND DISCUSSION

The following are some observations from the proof of Theorem 1:

**Observation 2.1** The proof uses the continuity of any one of the four maps S, T, f and g.

**Observation 2.2** The authors of Theorem 1 used only the weak commutativity of the self-maps.

**Observation 2.3** If *S* and *f* are weakly commuting and *g* is continuous, then they have a common fixed point, say *z* which will also be a common fixed point of the other weakly

commuting pair (T, g). It follows from (3) that z will be a common fixed point of all the four maps.

In view of the above remarks, Theorem 1 can be restated with significant corrections as follows:

**Theorem 1.** Let S, T, f and g be self-maps on a complete metric space X satisfying inclusions (2) and the inequality (3). Suppose that any one of the four maps S, T, f and g is continuous. Then

- (a) S and f will have a common fixed point z, provided they are weakly commuting. Further if (T,g) is also weakly commuting, then z will be a common fixed point of (T,g) as well.
- (b) (T,g) has a common fixed point z, provided they are weakly commuting. Further if (S,f) is also weakly commuting, then z will be a common fixed point of (S,f) as well.

If (S, f) and (T,g) are weakly commuting, then all the four maps S, T, f and g have a common fixed point in X. Indeed the common fixed point is unique.

Since neither compatibility nor weak compatibility is utilized in Theorem 1, it is appropriate to change the title of [13] as *Common fixed point for two pairs of weakly commuting self-maps on complete metric spaces*.

Moreover, the references of Jungck et al., Srinivas and U.M. Rao, Brown, Hua and Gao, Popa, and Renu Chug and Sanjay Kumar are <u>redundantly</u> mentioned in [9].

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