### An Efficient behavioural analysis of Graph Clustering Algorithms via Random Graphs

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### ABSTRACT

The proposed last research entitled "An Effective Data Comparison of Graph Clustering Algorithms via Random Graphs" compared two mostly used algorithms for graph clustering i.e. restricted neighborhood search and markov clustering algorithms via random graph generators i.e. Erdos-Renyi and power law graphs. This paper is an extension to our last research work. In this we have examined an efficient behavioral analysis of both algorithms via random graphs. This paper mainly shows the behavior of both the algorithms under certain parameters which we have used. Previously in case of Erdos-renyii we used graphs with 1000 nodes with variable edge densities, while in this paper we have modified the number of nodes from 1000 to 15000 with variable edge densities ranging from 0.1 to 0.5 while in case of Power-law we have variable number of nodes ranging from 1000 to 15000. This paper also depicts as to which algorithm works more efficient, whether in case of Erdos-Renyi or Power-Law graphs. Our last research showed that in case of Erdos-Renyi graph run time of RNSC algorithm is better as compared to MCL for graph having nodes less than 2000 but as nodes keep on increasing the run time of RNSC increases drastically while run time of MCL doesn't increase, so MCL is better in case of Erdos-Renyi graph having more than 2000 nodes and having high connectivity between the nodes [12] while in this paper it is clearly visible that both RNSC and MCL works better in case of Power-Law graph as compared to Erdos-Renyi graph which clearly states that both algorithm shows some similar characteristics in graphs where edge connectedness is not very high for all vertices. Furthermore we studied the behaviour of RNSC in case of Erdos-Renyi individually also.

### **General Terms**

Graph Clustering, Data mining et. al.

### Keywords

RNSC, MCL, Erdos-Renyi, Scaled-Free, Edge Density, Singleton Cluster, Run Time, Number of Nodes, Cluster Size.

### **1. INTRODUCTION**

We had already discussed about clustering and the main purpose for comparing both the clustering algorithms in our last paper. The previous work dealt in comparing both algorithms on basis of some graphs while some set of analysis still remained untouched which we had tried to cover in this segment of our work. The theories regarding both the algorithms and the graph generators had already been discussed in previous segment. This work is not basically a comparison but it is more of a behaviour analysis of both the algorithms via more modified graphs. We have implemented this work on gcc compiler version 4.6 (which can be obtained by running gcc -version in terminal) on Ubuntu operating system and all the graphs used in this analysis were unweighted and undirected.

### 2. PARAMETERS USED FOR COMPARISON

The parameters we considered in this research work are all the same as what we used previously i.e. Edge Density [12],Run time [12], Graph Size [12] and Cluster Size [12] but we excluded Singleton Cluster from our analysis. The theory regarding all the parameters used in our analysis has already been discussed in the previous paper.

### 3. RESULTS AND DISCUSSIONS

### 3.1 Results for RNSC

This section contains all the results and discussions regarding behaviour of RNSC in case of Erdos-Renyi and Power-Law graphs.

### 3.1.1 Number of Nodes vs RUN TIME in case of Erdos-Renvi only

The table contains computed values of graph size and run time in case of Erdos-Renyi graph with varying nodes and edge densities.

S.No	Node	Run	Run	Run	Run	Run
•	S	Time	Time	Time	Time	Time
		e=0.1	e=0.2	e=0.3	e=0.4	e=0.5
1.	1000	0.023	0.026	0.049	0.073	0.117
2.	2000	0.102	0.202	0.357	0.481	0.622
3.	3000	0.293	0.663	0.997	1.362	1.916
4.	4000	0591	1.264	2.058	3.071	4.257
5.	5000	1.024	2.674	3.947	6.109	8.859
6.	6000	1.803	3.908	6.772	10.77	14.84
7.	7000	2.831	5.98	10.28	16.85	25.46
8.	8000	4.31	9.03	14.74	25.30	250.6
9.	9000	5.732	13.02	23.71	38.63	57.91
10.	1000	8.915	17.70	32.58	51.96	84.15
	0					
11.	1100	10.80	22.72	46.14	74.67	103.8
	0					
12.	1200	14.62	30.95	58.36	95.03	139.1
	0					
13.	1300	17.85	50.18	73.84	126.9	62.87
	0					
14.	1400	23.14	34.63	91.25	161.5	236.4
	0					
15.	1500	26.96	60.32	115.5	205.3	281.3
	0					

Table 1: Dataset for RNSC in case of Erdos-Renyi

Discussion: Fig 1 shows a line graph representing Run Time versus graph size for a graph of nodes ranging from 1000 to 15000 and edge densities ranging from 0.1 to 0.5. This graph clearly states the behaviour of RNSC. We have represented the run time of RNSC for graphs having variable nodes and edge densities where the symbol (e) in the graph denotes the edge density for Erdos-Renyi graph. It is clearly visible from the graph that as the number of nodes and edge density is increased the run time of all the graphs also increased but in a linearly fashion but in case of graph (e=0.5) i.e. highest edge density the run time increased drastically and then came down as well and vice versa. This kind of behaviour we observed in our last work too. While the other graphs increased linearly with nodes. There was a sudden increase and fall in the run time of graph (e=0.2). This comparison of run time clearly shows that run-time of the RNSC increases sharply at the edge density of 25-50% i.e. half the edge pairs are connected. The number of moves is very high because the cost keeps fluctuating in this range due to diversification steps [12]. As the Edge-Density crosses 50%, the edge-connectivity of the graph increases and the diversification step has low effect on such high Edge-Density. So the run-time decreases, but still increases linearly as the Edge-Density increases [12]. Thus run time of RNSC gets highly affected due to increase in edge density and thus performance is poor against highly connected graphs.

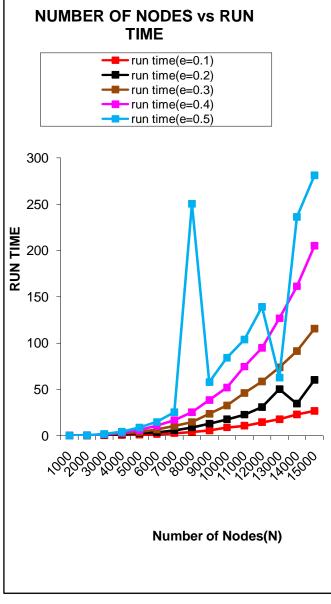


Fig 1: A line graph representing Number of Nodes vs RUN TIME for Erdos-Renyi graph with varying nodes and edge densities.

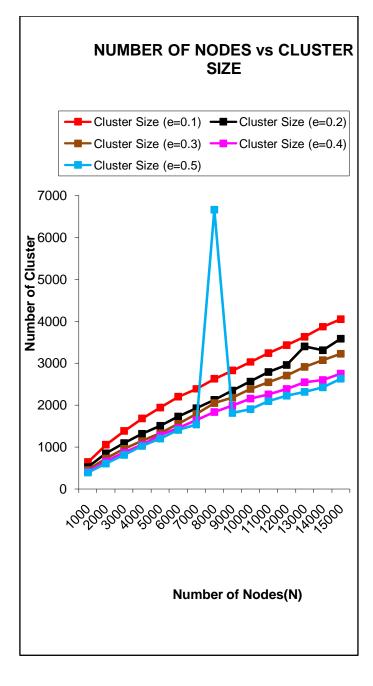
### 3.1.2 Number of Nodes vs Cluster Size in case of Erdos-Renyi only

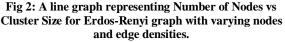
The table contains computed values of cluster size for Erdos-Renyi graph with varying nodes and edge densities.

Table 2. Dataset for RNSC in case of Erdos-Renyi

S.No	Nodes	0.1	0.2	0.3	0.4	0.5
•						
1.	1000	639	518	455	413	391
2.	2000	1051	849	729	660	607
3.	3000	1378	1089	956	868	811
4.	4000	1679	1316	1145	1055	1021
5.	5000	1939	1507	1333	1280	1204
6.	6000	2196	1727	1555	1453	1409
7.	7000	2385	1925	1787	1642	1538
8.	8000	2623	2126	2050	1836	6660
9.	9000	2823	2347	2177	1987	1813
10.	10000	3027	2564	2386	2154	1902
11.	11000	3238	2790	2545	2254	2097
12.	12000	3430	2960	2705	2383	2225
13.	13000	3627	3403	2907	2545	2315
14.	14000	3867	3308	3066	2595	2423
15.	15000	4047	3585	3221	2749	2629

Discussion: Fig 2 shows a line graph representing cluster size versus graph size for a graph of nodes ranging from 1000 to 15000 and edge densities ranging from 0.1 to 0.5. In previous paper Figure 5 showed a line graph representing Graph Size versus Cluster Size, where we analysed that as the number of nodes increased in the graph the number of clusters formed increase linearly, with the condition that the graph follows the same attribute like Edge-Density and connectivity. We saw that the number of clusters formed in the RNSC clustering is much higher than the MCL clustering for power-law graphs. From the graph we can easily analyse that cluster size also depends on the size of the graph and its edge density. The cluster size increased linearly with the graph size but as edge density is increased or the graph becomes more connected there is a sudden rise in cluster size. In case for graph (e=0.5) we see the same behaviour as the previous one i.e. cluster size increases drastically and then falls. While RNSC has a special feature of limiting the number of clusters which other algorithms do not have. We can limit the number of clusters in our case too. In the next comparison we will be comparing the behaviour of RNSC in case of Erdos-Renyi and Power-Law both.





## 3.1.3 Number of Nodes vs Cluster Size in case of Erdos-Renyi and Power-Law

The table contains computed values of Cluster Size and Number of Nodes in case of Erdos-Renyi & Power-Law.

S.No	Size of Graph	Cluster Size Erdos- Renyi(e=0.1)	Cluster Size Power- Law(alpha=2.5)
1.	1000	<u>391</u>	701
2.	2000	607	1414
3.	3000	811	2115
4.	4000	1021	2843
5.	5000	1204	3545
6.	6000	1409	4298
7.	7000	1538	5125
8.	8000	6660	6664
9.	9000	1813	6204
10.	10000	1902	7203
11.	11000	2097	8061
12.	12000	2225	8448
13.	13000	2315	9341
14.	14000	2423	9737
15.	15000	2629	10972

Table 3. Dataset for RNSC in case of Erdos-Renyi & Power-Law

Discussion: Fig 3 shows a line graph representing Number of Nodes versus Cluster Size for RNSC in case of both Erdos-Renyi and Power-Law graphs. The following graph depicts the behaviour of RNSC in case of both types of graphs i.e. Erdos-Renyi and Power-Law. The blue line represents cluster size for Erdos-Renyi while Red line represents cluster size for Power-Law. In case of Erdos-Renyi we have kept same edge density (e=0.1) for all graphs while in case of Power-Law the value of alpha is fixed to 2.5 for all the graphs. The cluster size for RNSC for Erdos-Renyi is same as what we discussed earlier i.e. Linear rise in the beginning and then sudden rise and fall in between 8000-10000 nodes while in case of Power-Law the cluster size increased linearly throughout its course. Another reason may be the large number of singleton clusters. Singleton clusters result due to the fact that the cost of the cluster decreases sometime with singleton cluster for sparsely connected graphs like power-law graphs [12]. Thus behaviour of RNSC is better for Power-Law graphs in the course of cluster formation.

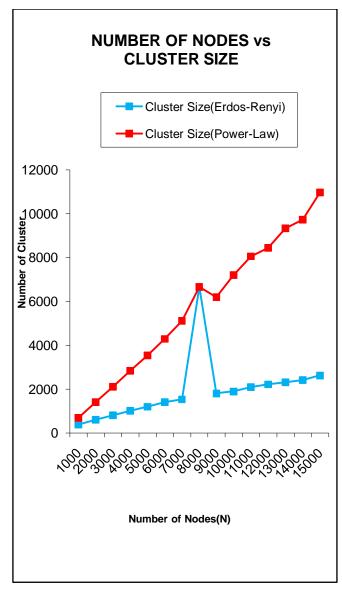


Fig 3: A line graph representing Number of Nodes vs Cluster Size in case of Erdos-Renyi & Power-Law.

3.1.4 Number of Nodes vs Run Time in case of Erdos-Renyi and Power-Law graphs

The table contains computed values of run time in case of Erdos-Renyi & Power-Law graphs with varying graph size.

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rower-Law				
S.No	Size of Graph	Runtime(Erdos- Renyi)	Runtime (Power- Law)	
1.	1000	0.117	0.053	
2.	2000	0.622	0.12	
3.	3000	1.916	0.232	
4.	4000	4.257	1.085	
5.	5000	8.859	0.542	
6.	6000	14.84	0.797	
7.	7000	25.46	1.891	
8.	8000	250.66	29.478	
9.	9000	57.91	0.981	
10.	10000	84.151	2.33	
11.	11000	103.893	5.036	
12.	12000	139.16	2.427	
13.	13000	62.873	9.53	
14.	14000	236.4	2.91	
15.	15000	281.332	18.425	

Table 4. Dataset for RNSC in case of Erdos-Renyi & Power-Law

**Discussion:** Fig 4 shows a line graph representing Number of Nodes versus run time for Erdos-Renyi and Power-Law graphs. In case of Erdos-Renyi the run time keeps on increasing exponentially because the run-time of the algorithm is inversely proportional to Tabu length i.e. the run time increases with the decrease in tabu length. Therefore for lesser run time large tabu length should be used. As the tabulength increases the number of moves which cannot be retraced increases, so there are fewer choices to make for the next move, thus the run-time decreases [13]. If the graph size is less then the run-time will be smaller. So as we decrease the maximum number of cluster which can be done in case of RNSC the run-time increases. While in case of Power-Law graph the run time stays a lot low.

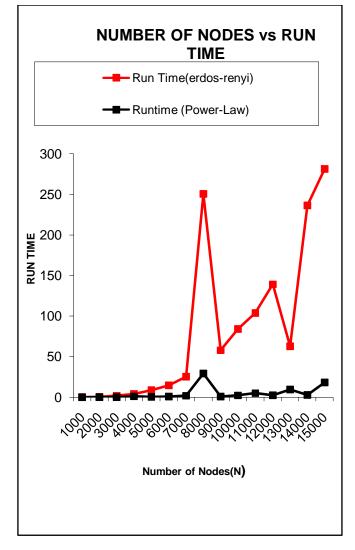


Fig 4: A LINE graph representing Graph Size vs Run Time in case of Erdos-Renyi & Power-Law

### 3.2 Results for MCL Graph

This section contains all the results and discussions regarding behaviour of MCL in case of Erdos-Renyi and Power-Law graphs.

#### 3.2.1 Number of Nodes vs Cluster Size

The table contains computed values of Cluster Size and Number of Nodes in case of Erdos-Renyi & Power-Law graphs.

S. No.	Numbe r of Nodes	Cluster Size (Erdos- Renyi(e=0.1)	Cluster Size Power- Law(α=2.5)
1.	1000	248	16
2.	2000	677	19
3.	3000	1297	15
4.	4000	2174	18
5.	5000	3220	14

Table 5. Dataset for MCL in case of Erdos-Renyi &Power-Law

**Discussion:** Figure 5 show a line graph representing graph size versus cluster size for both Erdos-Renyi and Power-Law graphs. More clusters can be seen in case of Erdos–Renyi as compared to Power-Law graph.

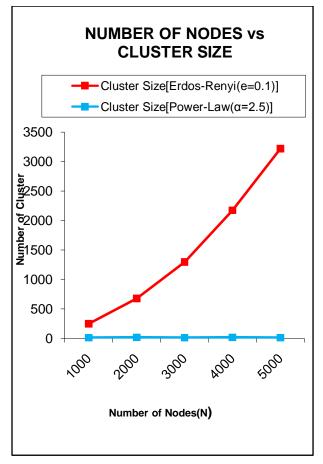


Fig 5: A line graph representing Number of Nodes vs Cluster Size in case of Erdos-Renyi & Power-Law.

#### 3.2.2 Number of Nodes vs Run Time

The table contains computed values of Run Time and Number of Nodes in case of Erdos-Renyi & Power-Law.

Table 6. Dataset for MCL in case of Erdos-Renyi & Power-Law

S. No.	Number of Nodes	Run Time Erdos- Renyi(e=0.1)	Run Time Power- Law(α=2.5)
1.	1000	127.377	3.82
2.	2000	2592.35	11.928
3.	3000	3254.026	12.844
4.	4000	16583.961	12.898
5.	5000	9617.616	14.806

**Discussion:** Fig 6 shows a line graph representing run time versus graph size for both Erdos-Renyi and Power-Law graphs. The pruning feature of MCL helps it to sustain a better performance than RNSC in case of run time, but performance of MCL is quite poor in case of strongly connected graphs. The graph clearly shows the behaviour of MCL in case of both graphs.

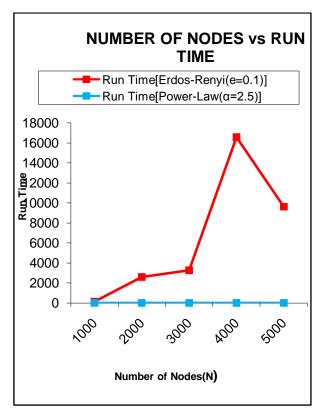


Fig 6: A line graph representing Number of Nodes vs Run Time in case of Erdos-Renyi & Power-Law.

# 4. CONCLUSIONS AND FUTURE WORK

On analyzing the whole scenario we came to the result that both algorithms have some advantages and disadvantages depending on what state and situation they are being applied. Run Time of MCL was better in case of Power-Law graph while Cluster Size was more in case of Erdos-Renyi, on the other hand RNSC showed better results mainly in case of Power-law graph. So the future work may be integrating the best parts of both the algorithms so that the performance may be enhanced. In our integration we may use Genetic algorithm so that heuristic approach of RNSC may be minimized too.

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