

A Note on Computational Approach to Travelling Sales Man Problem

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ABSTRACT

Many real life situations for which there are no optimization algorithms which can solve polynomial time problems in the worst case. So researchers are trying for new approximation algorithms for such kinds of situations. Approximation algorithms give the solution which is close to the optimal solution of a particular situation. Traveling Salesman Problem (TSP) is a typical NP complete problem which lacks polynomial time algorithm. In this paper it is proposed an edge removal algorithm, which will give the nearly optimal solution within a limited time.

General Terms

Optimization, Travelling Sales man Problem

Keywords

Edge Removal Algorithm, Compression Algorithm, Back Tracking.

1. INTRODUCTION

Traveling Salesman Problem (TSP) is a famous NP hard problem and also a typical combinatorial optimization problem in Operation Research. With the increasing of number of cities, its solving time complexity grows rapidly in exponential degree, so enumerating each possible route and searching for the one with the smallest cost to optimally solve this problem becomes impossible in polynomial time. In the classical traveling salesman problem, a set of cities has to be visited in a single tour with the objective of minimizing the total length of the tour. This is one of the most studied problems in combinatorial optimization, together with its dozens of variations. In the asymmetric version of the problem, the distance from one point to another in a given space can be different from the inverse distance. This variation, known as the Asymmetric Traveling Salesman Problem (ATSP) arises in many applications; for example, one can think of a delivery vehicle traveling through one-way streets in a city, or of gasoline costs when traveling through mountain roads.

2. THE TRAVELING SALESMAN PROBLEM

The idea of the traveling salesman problem (TSP) is to find a tour of a given number of cities, visiting each city exactly once and returning to the starting city where the length of this tour is minimized. TSP is of great significance in practical applications, it can be used to resolve the problems in allocation, path problem and vehicle scheduling problem and so on. The standard symmetric traveling salesman problem can be stated mathematically as follows:

Given a weighted graph $G = (V, E)$, where V is the set of nodes, E is the set of edges, and the weight c_{ij} on the edge between nodes i and j is a non-negative value, finding the tour of all nodes that has the minimum total cost.

3. EDGE REMOVAL ALGORITHM

Algorithm:

Step 1: Read the Adjacency Matrix, (distances between different towns).

Step 2: Apply compression algorithm on the above adjacency matrix, to remove edges and find cost tables.

Step 3: Sort the edges related to each node in ascending order.

Step 4: calculate the minimum cost array to improve the efficiency of this algorithm.

Step 5: Apply backtracking on the sorted cost tables obtained in step 3 using step 4 as an optimization step.

3.1 Example:

Step 1: Input:

0	2	8	15	1	10	5	19	19	3
5	0	6	6	2	8	2	12	16	3
8	17	0	12	5	3	14	13	3	2
17	19	16	0	8	7	12	19	10	13
8	20	16	15	0	4	12	3	14	14
5	2	12	14	9	0	8	5	3	18
18	20	4	2	10	19	0	17	16	11
3	9	7	1	3	5	9	0	7	6
11	10	11	11	7	2	14	9	0	10
4	5	15	17	1	7	17	12	9	0

Step 2: Compression Step:

In this step remove these edges that are no need to visit to find the optimal solution.

By using single source shortest path algorithms it can be find the shortest paths from a node to all remaining nodes. For example, consider node number 1, the paths from node 1 to all other nodes is like below.

Table1:

Source Node	Destination Node	Minimum Path	Node to be visited first	Cost
1	2	(1 2)	2	2
1	3	(1 3)	3	8
1	4	(1 5 8 4)	5	5

1	5	(1 5)	5	1
1	6	(1 5 6)	5	5
1	7	(1 2 7)	2	4
1	8	(1 5 8)	5	4
1	9	(1 5 6 9)	5	8
1	10	(1 10)	10	3

In the next case extract the fields' node to be visited first and cost where those values in the 2nd and 4th column of the above table are equal. That is, nodes extracted for the above table are 2, 3, 5, 10.

Now the cost tables are generated for above extracted nodes and their costs.

Table 2: Cost table for node 1.

Node Number	Cost
2	2
3	8
5	1
10	3

Cost tables for all the other nodes are given below:

Table 3: Cost Table for node 2.

Node Number	Cost
1	5
3	6
5	2
7	2
10	3

Table 4: Cost Table for Node 3.

Node Number	Cost
6	3
9	3
10	2

Table 5: Cost table for Node 4.

Node Number	Cost
5	8
6	7
9	10

Table 6: Cost Table for Node 5.

Node Number	Cost
6	4
8	3

Table 7: Cost Table for Node 6.

Node Number	Cost
1	5
2	2
8	5
9	3

Table 8: Cost Table for Node 7

Node Number	Cost
3	4
4	2

Table 9: Cost Table for Node 8.

Node Number	Cost
1	3
3	7
4	1
5	3
6	5
9	7
10	6

Table 10: Cost table for Node 9.

Node Number	Cost
6	2

Table 11: Cost table for Node 10.

Node Number	Cost
1	4
2	5
5	1

Step 3: Sort the above tables based on their ascending order of their costs.

Table 12: Sorted Cost table for Node 1.

Node Number	Cost
5	1
2	2
10	3
3	8

Cost tables for all the other nodes are given below:

Table 13: Sorted Cost Table for node 2.

Node Number	Cost
5	2
7	2
10	3
1	5
3	6

Table 14: Sorted Cost Table for Node 3.

Node Number	Cost
10	2
6	3
9	3

Table 15: Sorted Cost table for Node 4.

Node Number	Cost
6	7
5	8
9	10

Table 16: Sorted Cost Table for Node 5.

Node Number	Cost
8	3
6	4

Table 17: Sorted Cost Table for Node 6.

Node Number	Cost
2	2
9	3
1	5
8	5

Table 18: Sorted Cost Table for Node 7

Node Number	Cost
4	2
3	4

Table 19: Sorted Cost Table for Node 8.

Node Number	Cost
4	1
1	3
5	3
6	5
10	6
3	7
9	7

Table 20: Sorted Cost table for Node 9.

Node Number	Cost
6	2

Table 21: Sorted Cost table for Node 10.

Node Number	Cost
5	1
1	4
2	5

Step 4: Now calculate the minimum cost array

The minimum_cost_array size is equal to the number of nodes. So,

$$\begin{aligned} \text{minimum_cost_array}[1] &= \text{Sorted_Cost_Table}[1][2] = 1 \\ \text{Minimum_Cost_Array}[2] &= \text{minimum_Cost_Array}[1] + \text{Sorted_Cost_Table}[2][2] \\ &= 1 + 2 = 3. \\ \text{Minimum_Cost_Array}[3] &= \text{minimum_Cost_Array}[2] + \text{Sorted_Cost_Table}[3][2] \\ &= 3 + 2 = 5. \\ \text{Minimum_Cost_Array}[4] &= \text{minimum_Cost_Array}[3] + \text{Sorted_Cost_Table}[4][2] \\ &= 5 + 7 = 12. \\ \text{Minimum_Cost_Array}[5] &= \text{minimum_Cost_Array}[4] + \text{Sorted_Cost_Table}[5][2] \\ &= 12 + 3 = 15. \\ \text{Minimum_Cost_Array}[6] &= \text{minimum_Cost_Array}[5] + \text{Sorted_Cost_Table}[6][2] \\ &= 15 + 2 = 17. \\ \text{Minimum_Cost_Array}[7] &= \text{minimum_Cost_Array}[6] + \text{Sorted_Cost_Table}[7][2] \\ &= 17 + 2 = 19. \\ \text{Minimum_Cost_Array}[8] &= \text{minimum_Cost_Array}[7] + \text{Sorted_Cost_Table}[8][2] \\ &= 19 + 1 = 20. \end{aligned}$$

$$\begin{aligned} \text{Minimum_Cost_Array}[9] &= \text{minimum_Cost_Array}[8] + \text{Sorted_Cost_Table}[9][2] \\ &= 20 + 2 = 22. \end{aligned}$$

$$\begin{aligned} \text{Minimum_Cost_Array}[10] &= \text{minimum_Cost_Array}[9] + \text{Sorted_Cost_Table}[10][2] \\ &= 22 + 1 = 23. \end{aligned}$$

So, Minimum_Cost_Array[] =
{ 1, 3, 5, 12, 15, 17, 19, 20, 22, 23 }.

Step 5: Apply Backtracking step to the above cost Tables generated in Step 4:

The optimal tour is 1 5 8 4 9 6 2 7 3 10 1

Use of Step 4:

If you got a tour already, (and tour length is (say **OTL**))

For example, if there are 'N' cities, and the number of cities that to visited already is 'X', and the distance travelled already is 'D', Then it should travel atleast a distance of **Minimum_Cost_Array[n-x+1]** to get the next tour. So least possible distance for this tour is **D + Minimum_Cost_Array[n-x+1]**.

And it should satisfy the condition "**D + Minimum_Cost_Array[n-x+1] < OTL**", then only it can say the path (tour) that are travelling now can be a minimum tour than the earlier tour **OTL**. If above condition is failed to satisfy then skip the combinations to improve efficiency.

But, in some cases if the number of edges removed are very less, that mean the cost table size is high then this algorithm won't give the optimal result, in that situation it is better to go for nearly optimal solution.

3.2 Example:

Consider this 24 city problem:

The Adjacency Matrix for this problem is shown on separate sheet in the next page.

But to calculate the optimal path from normal backtracking method need 23! combinations, tht is, 25852016738884976640000 combinations have to be performed, so that it go for the nearly optimal solution. This approach is efficient to find the nearly optimal solution.

The Optimal solution for the problem is

16 11 3 7 6 24 8 21 5 10 17 22 18 19 15 2 20 14 13 9 23 4 12
1 Cost 1272

But to get the solution in a polynomial time is not possible, so by giving time bound of 15 seconds to Edge Removal Algorithm, will get the nearly optimal cost of 1316. This algorithm is checked against several samples of real world data and the results are promising to be nearly optimal. All the results shows this algorithm give the nearly optimal solution less than the 2 times of optimal solution in all possible cases.

The adjacency matrix [2.2] :

0	257	187	91	150	80	130	134	243	185	214	70	272	219	293	54	211	290	268	261	175	25	192	121
257	0	196	228	112	196	167	154	209	86	223	191	180	83	50	219	74	139	53	43	128	99	228	142
187	196	0	158	96	88	59	63	286	124	49	121	315	172	232	92	81	98	138	200	76	89	235	99
91	228	158	0	120	77	101	105	159	156	185	27	188	149	264	82	182	261	239	232	146	221	108	84
150	112	96	120	0	63	56	34	190	40	123	83	193	79	148	119	105	144	123	98	32	105	119	35
80	196	88	77	63	0	25	29	216	124	115	47	245	139	232	31	150	176	207	200	76	189	165	29
130	167	59	101	56	25	0	22	229	95	86	64	258	134	203	43	121	164	178	171	47	160	178	42
134	154	63	105	34	29	22	0	225	82	90	68	228	112	190	58	108	136	165	131	30	147	154	36
243	209	286	159	190	216	229	225	0	207	313	173	29	126	248	238	310	389	367	166	222	349	71	220
185	86	124	156	40	124	95	82	207	0	151	119	159	62	122	147	37	116	86	90	56	76	136	70
214	223	49	185	123	115	86	90	313	151	0	148	342	199	259	84	160	147	187	227	103	138	262	126
70	191	121	27	83	47	64	68	173	119	148	0	209	153	227	53	145	224	202	195	109	184	110	55
272	180	315	188	193	245	258	228	29	159	342	209	0	97	219	267	196	275	227	137	225	235	74	249
219	83	172	149	79	139	134	112	126	62	199	153	97	0	134	170	99	178	130	69	104	138	96	104
293	50	232	264	148	232	203	190	248	122	259	227	219	134	0	255	125	154	68	82	164	114	264	178
54	219	92	82	119	31	42	58	238	147	84	53	267	170	255	0	173	190	230	223	99	212	187	60
211	74	81	182	105	150	121	108	310	37	160	145	196	99	125	173	0	79	57	90	57	39	182	96
290	139	98	261	144	176	164	136	389	116	147	224	275	178	154	190	79	0	86	176	112	40	261	175
268	53	138	239	123	207	178	165	367	86	187	202	227	130	68	230	57	86	0	90	114	46	239	153
261	43	200	232	98	200	171	131	166	90	227	195	137	69	82	223	90	176	90	0	134	136	165	146
175	128	76	146	32	76	47	30	222	56	103	109	225	104	164	99	57	112	114	134	0	96	151	47
250	99	89	221	105	189	160	147	349	76	138	184	235	138	114	212	39	40	46	136	96	0	221	135
192	228	235	108	119	165	178	154	71	136	262	110	74	96	264	187	182	261	239	165	151	221	0	169
121	142	99	84	35	29	42	36	220	70	126	55	249	104	178	60	96	175	153	146	47	135	169	0

The nearly optimal solutions found based on this algorithm within 15 seconds is given below:

16 6 7 8 21 5 24 12 4 1 9 13 23 14 10 17 19 2 20 15 22 18 3 11	Cost 1509
16 6 7 8 21 5 24 12 4 1 9 13 23 14 10 17 2 20 15 19 22 18 3 11	Cost 1473
16 6 7 8 21 5 24 12 4 1 9 13 23 14 10 17 20 2 15 19 22 18 3 11	Cost 1457
16 6 7 8 21 5 24 12 4 1 9 13 23 14 20 2 15 19 10 17 22 18 3 11	Cost 1453
16 6 7 8 21 5 24 12 1 4 23 9 13 14 10 17 22 19 2 20 15 18 3 11	Cost 1443
16 6 7 8 21 5 24 12 1 4 23 9 13 14 10 17 19 2 20 15 22 18 3 11	Cost 1415
16 6 7 8 21 5 24 12 1 4 23 9 13 14 10 17 2 20 15 19 22 18 3 11	Cost 1379
16 6 7 8 21 5 24 12 1 4 23 9 13 14 10 17 20 2 15 19 22 18 3 11	Cost 1363
16 6 7 8 21 5 24 12 1 4 23 9 13 14 20 2 15 19 10 17 22 18 3 11	Cost 1359
16 6 7 8 21 5 24 10 17 3 11 18 22 19 2 15 20 14 13 9 23 4 12 1	Cost 1355
16 6 7 8 21 5 24 10 17 3 11 18 22 19 15 2 20 14 13 9 23 4 12 1	Cost 1331
16 6 7 8 21 24 5 10 17 3 11 18 22 19 15 2 20 14 13 9 23 4 12 1	Cost 1316

4. CONCLUSION

This paper proposed a novel algorithm to get nearly optimal solution to the Travelling Sales man problem by taking time bound as a limit. This algorithm uses single source shortest path algorithm to remove unnecessary edges and by using compression algorithm. This algorithm is tested against several real world data and results are promising.

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