Evaluation of Hybrid Topologies under Mobility of ZigBee Devices using Different Trajectories

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ABSTRACT

Wireless Sensor Network (WSN) is mostly used in real time applications, like as automobile traffic control, military purpose, medical area and environment examination. ZigBee is a Wireless Personal Area Network (WPAN) based on IEEE 802.15.4 wireless protocol. ZigBee gives short distance communication with low data rate, low power consumption and low complexity. In this paper the performance of hybrid topology is analyzed with OPNET Modeler 14.5 under the mobility of ZigBee End Devices (ZEDs) and ZigBee Coordinators (ZCs) using different trajectories in terms of load, traffic received and data drop. The Results show that when ZEDs and ZCs are move, the Mesh-Tree hybrid topology and Star-Tree hybrid topology gives best performance respectively. We also found that the performance of wireless sensor network for inner square and circle trajectories is superior to outer square trajectory.

Keywords

WSN, ZigBee, OPNET Modeler, Mobility, Trajectory.

1. INTRODUCTION

ZigBee was created by IEEE 802.15.4 task group and ZigBee alliance. To introduce wireless communication ZigBee cooperation makes some standards. This standard was produced to meet the accompanying important need of minimal cost, ultra low power utilization, utilization of unlicensed radio bands, simple implementation, adaptable and extendable systems [1, 3, and 7]. A WSN consists of many inexpensive wireless sensors, which are communicating with neighbouring nodes, processing environmental information, capable of collecting and storing. In the past, sensors are connected by wire lines. With the development of ad hoc networking technologies, tiny sensors can communicate through wireless links in a more convenient manner [2]. ZigBee works in the industrial, scientific and medicinal (ISM) radio band, particularly at 2.4 GHz globally and 868 MHz or 915 MHz in particular parts of the world. IEEE 802.15.4/ZigBee architecture ZigBee characterizes two layers of the OSI (Open Systems Interconnection) demonstrate: the Application layer and the Network layer. Every layer performs a particular arrangement of administrations for the layer above. The diverse layers communicate through Service Access Points (SAP's) [2, 5, and 9]. These SAPs encase two sorts of substances: (1) an information substance (NLDE-SAP) to give information transmission administration and (2) a management element (NLME-SAP) giving all the management services between layers. The application layer (APL) provide interface between the ZigBee systems to its end users and also defines the device functionality. The basic function of this layer is to convert the input into digital data, and/or converts digital data into output. The ZigBee Network

layer (NWK) is responsible for routing, network structure and security such as authentication, key management and encryption [8, 9]. It additionally encases the neighbor tables and the Stockpiling of related data. The NWK layer gives one arrangement of interfaces, the Network Layer Data Entity Service Access Point (NLDE-SAP) used to exchange information with the APS [10, 11].

1.1 ZigBee Device Object

As to device part in the network, ZigBee characterizes three sorts of devices: ZigBee Coordinator (ZC), ZigBee Router (ZR) and ZigBee End Device (ZED) [12, 14].

1.1.1 ZigBee Coordinator (ZC)

ZigBee coordinator is responsible for setting up all the network parameters such as topology, packet size etc. It is a node with superior computing capabilities as compared to routers and end-devices. It is a gateway for the outside world to interact with the network. This role is generally assigned to the sink node [11, 15].



Fig 1: ZigBee Devices

1.1.2 ZigBee Router (ZR)

ZigBee router is the intermediary device in a network which transmits data from the source to the destination as well as senses the data from their adjoining environment [3, 9].

1.1.3 ZigBee End Device (ZED)

ZigBee end-device is capable of sensing data and completely depends on their parents (routers/coordinators) for routing their packets with least computing capabilities [6, 8].

1.2 ZigBee Topologies

The ZigBee standard permits the arrangement of three sorts of network topology: Star, Tree, and Mesh [12, 13].

1.2.1 Star topology

It is the least difficult of the three topologies, comprising of just a solitary coordinator with various end-devices as its children [11, 14].



Fig 2: Star Topology

1.2.2 Tree topology

In this the devices compose themselves into a tree-like structure with the coordinator representing to the foundation of the tree, routers represent to the bases of sub-trees, and end-devices representing to leaves [7,9].





1.2.3 Mesh Topology

In mesh topology routers and coordinators shape various connections among one another while having end-devices as their children's. Albeit more unpredictable in its development and operation, network topology is described by link/path excess which is known not in enhanced system power and system steering capacity [12, 15].



Fig 4: Mesh Topology

1.2.4 ZigBee Hybrid Topologies

ZigBee hybrid topologies are the combination of two or more different topologies. There are many different combinations of topologies but we have used Star-Tree (ST), Star-Mesh (SM) and Tree-Mesh (TM) as ZigBee hybrid topologies.

1.3 ZigBee Coordinator and End Device Trajectories

During the entire simulation duration the sink keeps on moving on the same path and trajectory of sink movement is along fixed path.

1.3.1 Inner Square

In this trajectory, the coordinator and end device move inside the network field at some distance from the boundary generally half the distance from the centre forming a square.

1.3.2 Outer Square

In this trajectory, the coordinator and end device move outside the network field on the boundary forming a square.

1.3.3 Circle

In this trajectory, the coordinator and end device move on almost a circular path [16].

2. EXPERIMENTAL SETUP

In this paper the effect of mobility of ZigBee End Devices and ZigBee Coordinators on hybrid topologies (Star-Mesh, Star-Tree and Mesh-Tree) is analyzed by using different trajectories (Inner Square, Outer Square and Circle). To make hybrid topology two PAN coordinators are used with different trajectories. The various scenarios are made by using simulation parameters given in table 1. In this experiment firstly ZEDs are moving using different trajectories in each scenario under hybrid topologies and then ZCs are moving by using different trajectories in different scenarios under hybrid topologies. In each scenario there are 50 nodes which are placed randomly over an area of 100*100 which are moving with the speed of 12 m/s by using random way point model. In each scenario four ZRs are placed in each direction as shown in figure 5 which are fixed and two PAN coordinators is used. To get the performance of hybrid topology OPNET Modeler is used because OPNET Modeler provides a comprehensive development environment supporting the modeling of communication network and provides better environment for simulation, data collection and data analysis.



Fig 5: Scenario for Hybrid Topology

Parameters	Value	
Network Scale	100m*100m	
Number Of Nodes	50	
Network Type	Hybrid	
Mobility Model	Random Waypoint	
Speed of Mobile Nodes	10m/s	
Pause Time	100s	
Trajectories	Inner square, Outer Square and Circle	

Table 1: Simulation Parameters

3. RESULTS AND DISCUSSIONS

Simulation is conducted to evaluate the performance of hybrid topology under ZEDs and ZCs mobility by using different trajectories in terms of load, traffic received and packet dropped.

3.1 Load

Load represents the total load (in bits/sec) submitted to ZigBee 802.15.4 MAC by all higher layers in all wireless Personal Area Network (WPAN) nodes of the network. Figure 6, 7 and 8 shows the load variations of different hybrid topologies when ZigBee Coordinators and ZigBee End Devices are moving in circle, inner square and outer square trajectories. The graphs and Table 2, 3 shows that the load in ZigBee based wireless sensor network for MT hybrid topology is maximum under mobility of ZEDs in outer square trajectory and minimum under mobility of ZCs in inner square trajectory.



Fig 6: Load for Circle Trajectory



Fig 7: Load for Inner Square Trajectory



Fig 8: Load for Outer Square Trajectory

3.2 Traffic Received

Traffic received represents the total traffic successfully received by the MAC from physical layer in bits/sec. When these statistics are reported in units of bits/second, the physical and the MAC header sizes are included in the computation of the total amount of traffic received. These statistics record all the data received on the network interface regardless of the destination address. Graphs (Figure 9, 10 and 11) and Table 2, 3 describes the changes of traffic received with different hybrid topologies when ZigBee End Devices and ZigBee Coordinators are moving in circle, Inner Square and outer square trajectories. Traffic received in ZigBee based wireless sensor network for MT hybrid topology is maximum when ZEDs move in circle and inner square trajectories. When ST topology is used in the same network then minimum traffic is received under mobility of ZCs in circle trajectory.



Fig 9: Traffic Received for Circle Trajectory



Simulation Time

Fig 10: Traffic Received for Inner Square Trajectory



Fig 11: Traffic Received for Outer Square Trajectory

3.3 Packet Drop

Packet drop represents the drop by the layer due to not being joined to a network. This statistic records the total amount of data that was received from the upper layer and then dropped by all nodes in the network due to repeatedly failed retransmissions (i.e., exceeded the corresponding short retry or long retry threshold value). The packet drop rate of different hybrid topologies when ZigBee Coordinators and ZigBee End Devices are moving in outer square, circle and inner square trajectories are shown in figure 12, 13 and 14. It is found that minimum packets are dropped for ST topology when ZCs move in circle and inner square trajectories and for MT topology maximum packets are dropped under mobility of ZEDs in circle trajectory. The value of packet drop rate for hybrid topologies using different trajectories are mentioned in Table 2 and 3.



Fig 12: Packet Drop for Circle Trajectory



Fig 13: Packet Drop for Inner Square Trajectory



Fig 14: Packet Drop for Outer Square Trajectory

Trajectories	Hybrid	Load	Traffic	No. of
	Topologies	(bits/sec)	Received	Packet
			(bits/sec)	Drop
Circle	ST	130000	5400000	72
	MT	298000	10100000	81
	SM	139000	5100000	65
Inner square	ST	148000	5200000	66
	MT	300000	10100000	69
	SM	141000	5300000	63
Outer square	ST	145000	5995000	62
	MT	310000	10050000	72
	SM	148000	5200000	62

Table 2: Values of Different Parameters when ZEI)s Move
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 Table 3: Values of Different Parameters when ZCs Move

Trajectories	Hybrid Topologies	Load (bits/sec)	Traffic Received (bits/sec)	No. of Packet Drop
Circle	ST	158000	1800000	09
	MT	130000	2500000	55
	SM	161000	3300000	09
Inner square	ST	160000	2100000	09
	MT	122000	2190000	55
	SM	143000	2600000	15
Outer square	ST	162000	2210000	11
	MT	144000	2790000	43
	SM	162500	2730000	14

4. CONCLUSION

In this paper the effect of mobility of ZEDs and ZCs with hybrid topologies under different trajectories are concluded. To analyse the effect, 50 nodes are placed randomly and each node moves at a speed of 12m/s by using random way point model. The performance is compared on basis of load, traffic received and data drop. The results show that when ZigBee End Devices are moving then Mesh-Tree hybrid topology gives best performance for outer square trajectory in term of load and for circle and inner square trajectories in terms of traffic received. Further it is found that when ZigBee coordinators are moving then Star-Tree hybrid topology performs best for circle and inner square trajectories in terms of packet drop. Overall, it is found that circle and inner square trajectories based ZigBee wireless sensor network perform better in comparison to outer square trajectory. In future performance of ZigBee based wireless sensor network with hybrid topologies can be analysed by applying more complex trajectories.

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International Journal of Computer Applications (0975 – 8887) Volume 122 – No.20, July 2015

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