Fractional Calculus for Solving Generalized Abel’s Integral Equations using Chebyshev Polynomials

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ABSTRACT
In this paper we investigate the numerical solution of Abel’s integral equations of the first and second kind by Chebyshev polynomials of the first, second, third and fourth kinds. Some numerical examples are presented to illustrate the method.

General Terms
Numerical solutions, Fractional integral equations

Keywords
Singular Volterra integral equation, Abel’s integral equation, Fractional calculus, Chebyshev polynomial, Collocation points

1. INTRODUCTION
Abel’s integral equations provide an important tool for modeling a numerous phenomena in basic and engineering sciences such as physics, chemistry, biology, electronics and mechanics [4; 14; 20]. Abel’s integral equations often appears in two forms the first and second kind as follows.

\[ f(x) = \int_0^x \frac{u(t)}{\sqrt{x-t}} \, dt \]  \hspace{1cm} (1.1)

And

\[ u(t) = f(x) + \int_0^x \frac{u(t)}{\sqrt{x-t}} \, dt \]  \hspace{1cm} (1.2)

where \( f(x) \) is a continuous function with \( 0 \leq x, t \leq T \), where \( T \) is constant. Moreover, generalized Abel’s integral equation can be considered the following forms

\[ f(x) = \int_0^x \frac{u(t)}{(x-t)^{a}} \, dt \]  \hspace{1cm} (1.3)

And

\[ u(t) = f(x) + \int_0^x \frac{u(t)}{(x-t)^{a}} \, dt \]  \hspace{1cm} (1.4)

Where \( 0 < a < 1 \), \( f(x) \in C[0, T] \), \( 0 \leq x, t \leq T \) and \( T \) is constant.

The paper it organized the following way: In section 2, we present the fractional integral and derivative operators and some their properties. In section 3, we combined fractional technique, Chebyshev polynomials and the collocation method for solving Abel’s integral equation. Some examples are investigated in section 4. The numerical results show the accuracy of the method. Last section is conclusion that gives some points of the method.

2. FRACTIONAL INTEGRAL AND DERIVATIVE
Definition 2.1. A real function \( u(x), x > 0 \), is said to be in the space \( C_{\mu}, \mu \in R \) if there exists a real number \( \mu > 0 \) such that

\[ u(x) = x^\mu v(x), \text{ where } \]  \hspace{1cm} (2.1)

Proposition 2.1. The operator \( J^\alpha \) in definition 2.2 satisfies the following properties for \( u \in C_{\mu}, \mu \geq -1 \).

1. \( J^\alpha(u_i) = \sum_{i=0}^n f^\alpha u_i(x) \)
2. \( J^\alpha x^\beta = \int_0^\alpha x^{\alpha+\beta} \beta > -1 \)

Definition 2.3. The Riemann-Liouville fractional derivative of order \( \alpha \geq 0 \), of a function \( u(x) \in C_{\mu} \) is defined as

\[ f^\alpha u(x) = \frac{1}{\Gamma(\alpha)} \int_0^x (x-t)^{\alpha-1} u(t) \, dt \]  \hspace{1cm} (2.2)

where \( 0 < \alpha < 1 \), \( x > 0 \)

where \( f^\alpha u(x) \) means the first order derivative of \( u \).

Definition 2.4. The Cauchy fractional derivative of order \( \alpha \) is defined as

\[ f^\alpha f(x) = \frac{1}{\Gamma(m-\alpha)} \int_0^x (x-t)^{m-\alpha-1} f^{(m)}(t) \, dt \]  \hspace{1cm} (2.3)

Where, \( m-1 \leq \alpha \leq m, m \in N, x > 0 \) it has the following two basic properties

\[ f^\alpha f(x) = f(x) \]  \hspace{1cm} (2.4)

and

\[ f^\alpha f(x) = f(x) - \sum_{k=0}^{\infty} f^{(k)}(0^+) \frac{x^k}{k!}, \quad x > 0 \]  \hspace{1cm} (2.5)
3. DESCRIPTION OF THE METHOD

In this method, we use the Chebyshev polynomials through the fractional calculus to approximate the solution of Abel’s integral equations. So, we introduce briefly orthogonal Chebyshev polynomials as a suitable tool for approximation [7,18].

**Definition 3.1.** The Chebyshev polynomial \( T_n(t) \) of the first kind for \( t = \cos(\theta) \), \((0 \leq \theta \leq \pi)\), the function

\[
T_n(t) = \cos(n\theta) = \cos(n \cos^{-1}(t)) \quad (3.1)
\]

is a polynomial of degree \( n \). \( T_n(t) \) is called Chebyshev polynomial of degree \( n \). When \( \theta \) increases from 0 to \( \pi \), \( t \) decreases from 1 to \(-1\). Then the interval \([-1,1]\) is domain of definition of \( T_n(t) \). Also, the roots of Chebyshev polynomial of degree \( n + 1 \) can be obtained by the following formula

\[
t_i = \cos\left(\frac{(2i-1)\pi}{2(n+1)}\right), \quad i = 1, ..., n + 1 \quad (3.2)
\]

In addition, the successive Chebyshev polynomials can be obtained by the following recursive relation

\[
\begin{align*}
T_0(x) &= 1, \\
T_1(x) &= x, \\
T_2(x) &= 2x^2 - 1, \\
T_n(x) &= 2xT_{n-1}(x) - T_{n-2}(x), & n &= 2, 3, 4, ...
\end{align*} \quad (3.3)
\]

**Definition 3.2.** The Chebyshev polynomial \( U_n(t) \) of the second kind for \( t = \cos(\theta) \), \((0 \leq \theta \leq \pi)\) the function

\[
U_n(t) = \frac{\sin((n+1)\theta)}{\sin(\theta)} \quad (3.4)
\]

is a polynomial of degree \( n \). \( U_n(t) \) is called Chebyshev polynomial of degree \( n \). When \( \theta \) increase from 0 to \( \pi \), \( t \) decrease from 1 to \(-1\). Then the interval \([-1,1]\) is domain of definition of \( U_n(t) \). Also, the roots of Chebyshev polynomial of degree \( n + 1 \) can be obtained by the following formula

\[
t_i = \cos\left(\frac{(2i-1)\pi}{2(n+2)}\right), \quad i = 1, ..., n + 1 \quad (3.5)
\]

In addition, the successive Chebyshev polynomials can be obtained by the following recursive relation

\[
\begin{align*}
U_0(x) &= 1, \\
U_1(x) &= 2x, \\
U_2(x) &= 4x^2 - 1, \\
U_n(x) &= 2xU_{n-1}(x) - U_{n-2}(x), & n &= 2, 3, 4, ...
\end{align*} \quad (3.6)
\]

**Definition 3.3.** The Chebyshev polynomial \( V_n(t) \) of the second kind for \( t = \cos(\theta) \), \((0 \leq \theta \leq \pi)\) the function

\[
V_n(t) = \frac{\cos((n+1)\theta)}{\cos(\theta)} \quad (3.7)
\]

is a polynomial of degree \( n \). \( V_n(t) \) is called Chebyshev polynomial of degree \( n \). When \( \theta \) increase from 0 to \( \pi \), \( t \) decrease from 1 to \(-1\). Then the interval \([-1,1]\) is domain of definition of \( V_n(t) \). Also, the roots of Chebyshev polynomial of degree \( n + 1 \) can be obtained by the following formula

\[
t_i = \cos\left(\frac{(2i-1)\pi}{2(n+3)}\right), \quad i = 1, ..., n + 1 \quad (3.8)
\]

In addition, the successive Chebyshev polynomials can be obtained by the following recursive relation

\[
\begin{align*}
V_0(x) &= 1, \\
V_1(x) &= 2x - 1, \\
V_2(x) &= 4x^2 - 2x - 1, \\
V_n(x) &= 2xV_{n-1}(x) - V_{n-2}(x), & n &= 2, 3, 4, ...
\end{align*} \quad (3.9)
\]

**Definition 3.4.** The Chebyshev polynomial \( W_n(t) \) of the second kind for \( t = \cos(\theta) \), \((0 \leq \theta \leq \pi)\) the function

\[
W_n(t) = \frac{\sin((n+1)\theta)}{\sin(\theta)} \quad (3.10)
\]

is a polynomial of degree \( n \). \( W_n(t) \) is called Chebyshev polynomial of degree \( n \). When \( \theta \) increases from 0 to \( \pi \), \( t \) decrease from 1 to \(-1\). Then the interval \([-1,1]\) is domain of definition of \( W_n(t) \). Also, the roots of Chebyshev polynomial of degree \( n + 1 \) can be obtained by the following formula

\[
t_i = \cos\left(\frac{(2i-1)\pi}{2(n+3)}\right), \quad i = 1, ..., n + 1 \quad (3.11)
\]

In addition, the successive Chebyshev polynomials can be obtained by the following recursive relation

\[
\begin{align*}
W_0(x) &= 1, \\
W_1(x) &= 2x + 1, \\
W_2(x) &= 4x^2 + 2x - 1, \\
W_n(x) &= 2xW_{n-1}(x) - W_{n-2}(x), & n &= 2, 3, 4, ...
\end{align*} \quad (3.12)
\]

Now, we apply Chebyshev polynomials for solving Abel’s integral equation of the first and second kind.

3.1. First kind

According to (1.3) and (2.1), Abel’s integral equation of the first kind can be rewritten as follow

\[
f(x) = \Gamma(1-\alpha)\int_{a}^{x}u(x) \quad (3.13)
\]

Since calculating of \( \int_{a}^{x}u(x) \) is directly cost and inefficient, we will use Chebyshev polynomials for approximating \( u(x) \). We assume \( u(x) \) on interval \([-1,1]\), can be written as a infinite series of Chebyshev basis

\[
u(x) = \sum_{i=0}^{\infty} a_i G_i(x), \quad (3.14)
\]

where \( G_i(x) = T_i(x), U_i(x), V_i(x) \) and \( W_i(x) \) are the first, second, third and forth kind of chebyshev polynomials. For interval \([a,b]\), we can use suitable change of variable to obtain this interval. So we express \( u(x) \) as a truncated Chebyshev series as follow
such that \( u_n(x) \) will be approximated solution of Abel’s integral equation. Now, we can write (3.13) in the form

\[
\sum_{i=0}^{n} a_i G_i(x) = f(x) + \Gamma(1 - a) \sum_{i=0}^{n} a_i f^{1-a} G_i(x)
\]  

(3.23)

or equivalently by using (3.20)

\[
\sum_{i=0}^{n} a_i G_i(x) = f(x) + \Gamma(1 - a) \sum_{i=0}^{n} c_i f^{1-a} x^i
\]  

(3.24)

After computing \( f^{1-a} x^i \) and substitute the collocation points we have a system of linear equations. Solution of the system leads to the approximated solution of Abel’s integral equation. We solve some examples by this method and assess the accuracy of method in the next section.

4. NUMERICAL EXAMPLES

This section is devoted to computational results. We apply the presented method in this paper and solve several examples. Those examples are chosen whose exact solutions exist. All of the computations have been done using the Maple 16.

Example 1. Consider Abel’s integral equation

\[
\frac{1}{\sqrt{x}} - \frac{u(t)}{\sqrt{x-t}} dt = \frac{2}{105} \sqrt{x(105 - 56x^2 + 48x^3)}
\]  

(4.1)

with the exact solution \( x^2 - x^2 + 1 \) [17, 3, 21]. Applying chebyshev polynomials of the first kind to integral equation (4.1) at \( n = 3 \), we obtain the approximate solution which is the same as the exact solution. Similarly in all cases of chebyshev polynomials.

Note: We note that if the exact solution is a polynomial of degree \( k \), the solution is the same as the exact solution for all \( n > k \).

Example 2. Consider the following Abel’s integral equation of the second kind

\[
u(x) = \frac{16}{15} x^2 - \frac{5}{x} \frac{u(t)}{\sqrt{x-t}} dt
\]  

(4.2)

with exact solution \( x^2 \) [15, 17, 3, 21]. Similar to the previous example, applying chebyshev polynomials of the second kind to integral equation (4.2) at \( n = 2 \), we obtain the approximate solution which is the same as the exact solution. Similarly in all cases of chebyshev polynomials.

Example 3. Consider the following Abel’s integral equation of the second kind

\[
u(x) = \frac{1}{2} \pi x + \sqrt{x} - \frac{x}{\sqrt{x-t}} \frac{u(t)}{\sqrt{x-t}} dt
\]  

(4.3)

with exact solution \( u(x) = \sqrt{x} \) [3]. The numerical results are shown in Table 1.

Example 4. Consider the following Abel’s integral equation of the first kind
with the exact solution $u(x) = \frac{x}{2\sqrt{x}}$. The numerical results are shown in Table 2.

**Example 5.** Consider the following Abel’s integral equation of the first kind

$$\int_{0}^{x} \frac{u(t)}{\sqrt{x-t}} \, dt = \frac{2}{3\sqrt{3}} \, \pi x$$  \hspace{1cm} (4.5)

with exact solution $u(x) = \sqrt{x}$. The numerical results are shown in Table 4.

Table 1: Estimate the exact, approximate solution and error of Example 3.

<table>
<thead>
<tr>
<th>Chebyshev at n = 5</th>
<th>First kind</th>
<th>Second kind</th>
<th>Third kind</th>
<th>Fourth kind</th>
</tr>
</thead>
<tbody>
<tr>
<td>x</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.1</td>
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<tr>
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<td>0.1162422174</td>
</tr>
<tr>
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</tr>
<tr>
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<tr>
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</tr>
<tr>
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</tr>
</tbody>
</table>

Table 2: Estimate the exact, approximate solution and error of Example 4.

<table>
<thead>
<tr>
<th>Chebyshev at n = 5</th>
<th>First kind</th>
<th>Second kind</th>
<th>Third kind</th>
<th>Fourth kind</th>
</tr>
</thead>
<tbody>
<tr>
<td>x</td>
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<td></td>
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</tbody>
</table>

Table 3: Estimate the exact, approximate solution and error of Example 5.
Table 4: Estimate the exact, approximate solution and error of Example 6.

<table>
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<th>Chebyshev at n = 5</th>
<th>First kind</th>
<th>Fourth kind</th>
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<tbody>
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<td>Exact</td>
<td>Approximate</td>
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</table>

We note that the second and third kind of chebyshev polynomials are similar.

5. CONCLUSION
In this method, we develop the Chebyshev method through the fractional calculus for solving generalized Abel's integral equations. We note that this method is easy to compute. Also, ability and efficiency of the method are great. In particular, when the exact solution of the problem is polynomial, the method gives the exact solution.

6. REFERENCES